

Product Manual

SBE 33 Carousel Deck Unit

For use with PDIM, SBE 32 Carousel Water Sampler, or SBE 55 ECO Water Sampler



Front Panel – switches & LEDs



Back Panel - connectors & fuses

01/30/18
017
3.0c & later
Seasave V7 7.26.7 & later

CE

service@seabird.com | support@seabird.com | Tel: +1 425 643 9866

Limited Liability Statement

Extreme care should be exercised when using or servicing this equipment. It should be used or serviced only by personnel with knowledge of and training in the use and maintenance of oceanographic electronic equipment.

SEA-BIRD ELECTRONICS, INC. disclaims all product liability risks arising from the use or servicing of this system. SEA-BIRD ELECTRONICS, INC. has no way of controlling the use of this equipment or of choosing the personnel to operate it, and therefore cannot take steps to comply with laws pertaining to product liability, including laws which impose a duty to warn the user of any dangers involved in operating this equipment. Therefore, acceptance of this system by the customer shall be conclusively deemed to include a covenant by the customer to defend, indemnify, and hold SEA-BIRD ELECTRONICS, INC. harmless from all product liability claims arising from the use or servicing of this system.

Declaration of Conformity

Sea-Bird Electronics, Inc. 13431 NE 20th Street Bellevue, WA 98005

DECLARATION OF CONFORMITY

Manufacturer's Name:	Sea-Bird Electronics
Manufacturer's Address:	13431 NE 20th Street Bellevue, WA 98005, USA

Device Description: Various Data Acquisition Devices and Sensors

Model Numbers:

3S	3F	3plus	4C	4M	5M	5T
5P	7	8	9plus	11plusV2	14	16plusV2
16plusIM-V2	17plusV2	18	19plusV2	21	25plus	26plus
27	29	32	32C	32SC	33	35
35RT	36/PDIM	37-SI	37-SIP	37-IM	37-IMP	37-SM
37-SMP	38	39	39-IM	39plus	41	41CP
43	43F	44	45	48	49	50
52-MP	53	54	55	56	63	PN 90204
PN 90158.1	PN 90488	PN 90545	PN 90402	AFM	SIM	ICC
IMM/UIMM	Glider Payload CTD	NiMH Battery Charger & Battery Pack (PN 90504)				

Applicable EU Directives: Machinery Directive 2006/42/EC

EMC Directive 2004/108/EC

Low Voltage Directive (2006/95/EC)

Applicable Harmonized Standards:

EN 61326-1:2013 Class A Electrical Equipment for Measurement, Control and Laboratory Use, EMC Requirement - Part 1: General Requirements (EN 55011:2009 Group 1, Class A)

EN 61010-1:2010, Safety Requirements for Electrical Equipments for Measurement, Control, and Laboratory Use - Part 1: General Requirements

I, the undersigned, hereby declare that the equipment specified above conforms to the above European Union Directives and Standards.

	<u> </u>
Authorized Signature:	Carry M-2
Name:	Casey Moore
Title of Signatory:	President
Date:	June 6, 2014
Place:	Belleview, WA

Table of Contents

Limited Liability Statement	2
Declaration of Conformity	3
Table of Contents	4
Section 1: Introduction	6
About this Manual Unpacking SBE 33	
Section 2: Description of SBE 33	
System Description	
Specifications	11
PDIM Dimensions and Connectors	
SBE 33 Front Panel	
SBE 33 Back Panel Cables and Wiring	
System Communications	
NMEA and Surface PAR	
Section 3: Setting Up System	20
Installing Software	
Setting CTD Baud Rate and Operating Parameters	
SBE 19, 19 <i>plus</i> (not 19 <i>plus</i> V2), 25 (not 25 <i>plus</i>), or 49	21
SBE 19plus V2 or 25plus	
Setting Up and Testing System	
Changing Communication Settings between SBE 33 and Computer	
Checking CTD Configuration (.xmlcon or .con) File in Seasave	
Section 4: Mounting and Wiring System	
Cable, Winch, and Deck Gear (not supplied by Sea-Bird)	29
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33	29 29
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System	29 29 30
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD	29 29 30 30
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System	29 29 30 30 30
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33	29 29 30 30 30 30 31
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33	29 30 30 30 30 30 31 31
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33	29 30 30 30 30 30 31 31
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System	29 30 30 30 30 31 31 31 31
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Surface PAR Sensor to SBE 33 Acquiring Real-Time Data and Firing Bottles from Seasave	29 30 30 30 31 31 31 31 31 31
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System Acquiring Real-Time Data and Firing Bottles from Seasave Firing Bottles from SBE 33 Front Panel	29 30 30 30 31 31 31 31 32 32 36
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System Acquiring Real-Time Data and Firing Bottles from Seasave Firing Bottles from SBE 33 Front Panel Recovering CTD and Water Sampler	29 30 30 30 31 31 31 31 32 32 36 37
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Acquiring Real-Time Data and Firing Bottles from Seasave Firing Bottles from SBE 33 Front Panel Recovering CTD and Water Sampler Uploading CTD Data from Memory	29 29 30 30 31 31 31 32 32 36 37 38
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System Acquiring Real-Time Data and Firing Bottles from Seasave Firing Bottles from SBE 33 Front Panel Recovering CTD and Water Sampler	29 30 30 31 31 31 32 36 37 38 38
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33	29 29 30 30 31 31 31 32 36 37 38 38 39
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System Acquiring Real-Time Data and Firing Bottles from Seasave Firing Bottles from SBE 33 Front Panel Recovering CTD and Water Sampler Uploading CTD Data from Memory Processing Data Using SBE Data Processing Editing Raw Data File.	29 30 30 31 31 31 32 36 37 38 38 39 40
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System Acquiring Real-Time Data and Firing Bottles from Seasave. Firing Bottles from SBE 33 Front Panel Recovering CTD and Water Sampler Uploading CTD Data from Memory. Processing Data Using SBE Data Processing Editing Raw Data File. Section 6: Routine Maintenance	29 29 30 30 31 31 31 32 36 37 38 38 39 40
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33 Wiring System Water Sampler or PDIM to CTD Sea Cable from SBE 33 to Water Sampler or PDIM SBE 33 to Computer Power to SBE 33 NMEA Navigation Device to SBE 33 Surface PAR Sensor to SBE 33 Surface PAR Sensor to SBE 33 Section 5: Operating System Acquiring Real-Time Data and Firing Bottles from Seasave Firing Bottles from SBE 33 Front Panel Recovering CTD and Water Sampler Uploading CTD Data from Memory. Processing Data Using SBE Data Processing Editing Raw Data File Section 6: Routine Maintenance Connector Mating and Maintenance	29 30 30 30 31 31 31 32 32 36 37 38 38 39 40 40
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33	29 29 30 30 31 31 31 32 36 37 38 39 40 40 41
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33	29 29 30 30 31 31 31 32 36 37 38 39 40 40 41
Cable, Winch, and Deck Gear (not supplied by Sea-Bird) Mounting SBE 33	29 29 30 30 31 31 31 32 36 37 38 38 39 40 40 41 41

Problem 4: Unsupported Modem Message (FFFFFFF Unsupported modem message: XX XX) from Water Sampler Problem 5: Yellow <i>NMEA Transmit</i> LED Not Flashing Problem 6: Yellow <i>NMEA Transmit</i> LED Flashing, but Lat/Lon Data Not Displaying	43
Glossary	. 44
Safety and Electrical Symbols	45
Appendix I: NMEA Navigation Device Message and Data Forma	ats46
Message Formats Data Formats	
Appendix II: NMEA Message Simulation Program	. 48
Appendix III: PDIM Electronics Disassembly/Reassembly	. 50
Appendix IV: Replacement Parts	. 51
Appendix V: Manual Revision History	. 52
Index	. 54

Section 1: Introduction

This section includes photos of a typical SBE 33 shipment.

About this Manual

This manual is to be used with the SBE 33 Carousel Deck Unit. It is organized to guide the user from installation through operation. We've included detailed specifications, setup and operation descriptions, and helpful notes throughout the manual.

The SBE 33 can be used with an SBE 32 Carousel Water Sampler or an SBE 55 ECO Water Sampler, and with a number of Sea-Bird CTDs. See the appropriate water sampler manual for details on rigging the water sampler for operation; see the appropriate CTD manual for CTD setup.

The SBE 33 can also be used with the Power and Data Interface Module (PDIM) and a number of Sea-Bird CTDs when a Water Sampler is not available or needed. The PDIM provides the same power and CTD data interface functionality as the SBE 32 or 55 Water Sampler, but without water sampling capability.

Sea-Bird welcomes suggestions for new features and enhancements of our products and/or documentation. Please contact us with any comments or suggestions (seabird@seabird.com or 425-643-9866). Our business hours are Monday through Friday, 0800 to 1700 Pacific Standard Time (1600 to 0100 Universal Time) in winter and 0800 to 1700 Pacific Daylight Time (1500 to 0000 Universal Time) the rest of the year.

Unpacking SBE 33

Shown below is a typical SBE 33 shipment. Inclusion of test cables, etc. is dependent on the order.



SBE 33 Carousel Deck Unit



Rack mount kit (screws not shown)



Computer to SBE 33 cable for Serial Data & Carousel Data connectors (2 cables / SBE 33)



Sea Cable connector (at SBE 33 end of cable)



SBE 33 power cable



SBE 33 to Water Sampler test cable



NMEA Input connector



NMEA Input Interface test cable

Software, and Electronic Copies of Software Manuals and User Manual

Section 2: Description of SBE 33

This section describes the functions and features of the SBE 33 Carousel Deck Unit, as well as system communications.

System Description

Notes:

- The SBE 32 Carousel is a 12-, 24-, or 36-bottle water sampler. The SBE 55 ECO is a 3- or 6-bottle water sampler.
- Seasave also supports acquisition of data from a NMEA device connected directly to the computer (instead of the deck unit).
- Surface PAR channel was optional in earlier versions of the SBE 33.
- SBE 25: If the SBE 25 is integrated with more than 4 auxiliary voltage sensors, and the SBE 33 is appending both NMEA and Surface PAR, you must set the SBE 25 realtime output rate to 4 scans/sec or less (see the SBE 25 manual for command details).
- SBE 25*plus*: If the SBE 33 is appending both NMEA and Surface PAR, you must slow down the realtime output rate by setting **SetHistoricRate=0** (see the 25*plus* manual for command details).
- SBE 49: Seasave 7.23.2 and later supports acquisition of Surface PAR data.

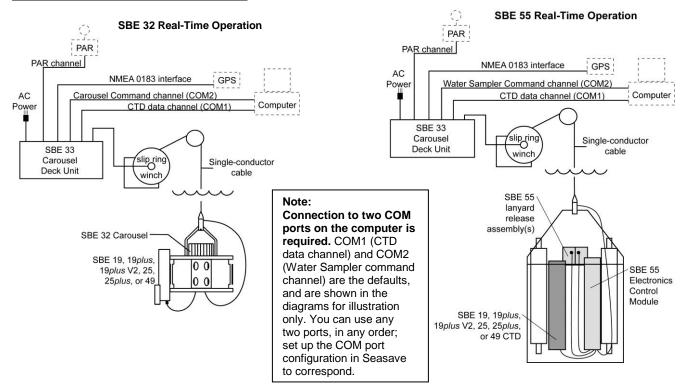
The SBE 33 Carousel Deck Unit provides power and real-time data acquisition and control for an **SBE 32 Carousel Water Sampler** that has the SBE 33 interface feature installed in its pylon. The SBE 33 is compatible with all Carousel sizes – full size (can close up to 24 bottles), compact, and subcompact. When powered and controlled by the SBE 33, the Carousel can be used with:

- SBE 19, 19plus, 19plus V2, 25, 25plus, or 49 CTD
- No CTD
- Neil Brown MK III CTD (requires interface; contact Sea-Bird)

The SBE 33 can also be used to provide power and real-time data acquisition and control for an **SBE 55 ECO Water Sampler** used with an SBE 19, 19*plus*, 19*plus* V2, 25, 25*plus*, or 49 CTD or no CTD.

The SBE 33 / Water Sampler system provides continuous real-time data telemetry and surface power for the CTD, and permits Water Sampler control through the SBE 33 and via our Seasave software. Bottles may be fired sequentially or any order.

The rack-mountable SBE 33 supplies DC power for the underwater unit, decodes the serial data, and passes the data to a computer. The SBE 33 back-panel switch permits continuous operation from 120 VAC or 240 VAC 50/60 Hz input power. The front-panel LED display indicates which bottles have been fired.



Notes:

- For NMEA depth data (DBT or DPT):
- Depth data can be decoded and merged with CTD data only if NMEA position data (GGA, GLL, RMA, RMC, or TRF) is also available.
- Seasave (real-time data acquisition software) and SBE Data Processing (post-processing software) are compatible with NMEA depth data in the data stream.

Note:

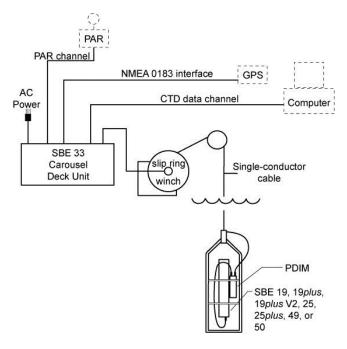
This manual describes the primary use of the SBE 33 with a CTD and Water Sampler. Setup for use with a CTD and PDIM is the same, except as noted. The SBE 33 can merge position data with CTD data. The SBE 33 decodes messages that are output from navigation devices supporting NMEA 0183 protocol, in one or more of the following formats:

- GGA Global Positioning System Fix Data
- GLL Geographic Position: Latitude/Longitude
- RMA Recommended Minimum Specific Loran-C Data
- RMC Recommended Minimum Specific GPS/TRANSIT Data
- TRF TRANSIT Fix Data
- DBT Depth Below Transducer
- DPT Depth

Decoded NMEA data is appended to the CTD data stream in the SBE 33, and are passed to the computer for storage and/or display with the CTD data.

The SBE 33 includes an A/D converter for a Surface PAR light sensor. The SBE 33 supplies 12 volts to power the sensor, and appends the data to the CTD data stream.

The SBE 33 can also be used with the Power and Data Interface Module (PDIM) and a number of Sea-Bird CTDs when a Water Sampler is not available or needed. The PDIM provides the same power and CTD data interface functionality as the SBE 32 or 55 Water Sampler, but without water sampling capability. The PDIM is mounted to the CTD.



Notes:

- Help files provide detailed information on the software.
- NMEATest, a NMEA navigation device simulation program, is part of the SBE Data Processing installation.
- Separate software manuals on CD-ROM contain detailed information on Seasave and SBE Data Processing.
- Sea-Bird supplies the current version of our software when you purchase an instrument. As software revisions occur, we post the revised software on our website. See our website for the latest software version number, a description of the software changes, and instructions for downloading the software.

The SBE 33 is supplied with a powerful Windows software package, Seasoft V2, which includes:

- Seaterm and SeatermV2 terminal programs for easy setup.
- Seasave V7 program for acquiring, converting, and displaying real-time or archived raw data.
- SBE Data Processing program for calculation and plotting of conductivity, temperature, pressure, auxiliary sensor data, and derived variables such as salinity and sound velocity.

NOTES:

CTD types, and can be controlled in several ways:	

Data Acquisition and Control	СТД	Control
	SBE 9plus	SBE 11plus Deck Unit
Real-Time	SBE 19 / 19plus / 19plus V2/ 25 / 25plus / 49	SBE 33 Deck Unit
	Neil Brown MK III	(this manual)
	None	
	SBE 9plus	SBE 17 <i>plus</i> V2 Searam
Autonomous (no conducting wire required)	SBE 19/19plus/19plus V2/ 25/25plus	
	SBE 50 Pressure Sensor	Auto Fire Module (AFM)
	None	

For details on the Carousel use for each combination, see the appropriate control manual (this manual, or SBE 11*plus*, SBE 17*plus* V2, or AFM manual).

2. The SBE 55 ECO Water Sampler can be used with several Sea-Bird CTD types, and can be controlled in several ways:

Data Acquisition and Control	СТД	Control
Real-Time	SBE 19 / 19plus / 19plus V2 / 25 / 25plus / 49	SBE 33 Deck Unit
	None	(this manual)
Autonomous (no conducting	SBE 19/19plus/19plus V2/ 25/25plus	Built-in auto-fire feature in SBE 55; see SBE 55 manual
wire required)	None	for operating details

Specifications

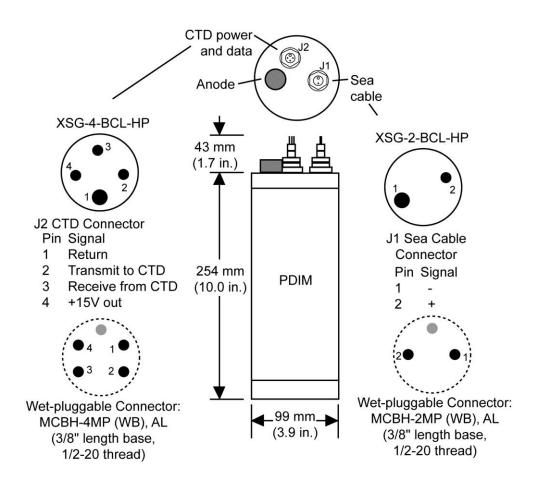
The SBE 33 supplies a constant 250 VDC power to the sea cable. The Water Sampler or PDIM receives this voltage (minus the sea cable IR drop) and regulates it to a constant 64 VDC. This 64 VDC is input to a high-efficiency DC/DC converter, which outputs + 15 VDC. The +15 VDC is the supply voltage to the CTD. Approximately 1 amp, *in addition to CTD power*, is available at the CTD for support of auxiliary sensors.

Power Requirements	120VAC at 60Hz and 1.75A or 240VAC at 50Hz and 1A switchable		
Sea Cable Compatibility	Single or multi-core armored cable up to 10,000 m (32,800 ft) long with inner core resistance of up to 350 ohms		
Water	SBE 32 Carousel Water Sampler (any size). If using with 36-bottle Carousel, can only close 24 bottles.		
Sampler Compatibility	SBE 55 ECO Water Sampler		
Compationity	PDIM		
Dimensions and Weight	9 cm tall x 37.5 cm deep x 44.4 cm wide cabinet; 46.4 cm edge-to-edge for mounting brackets (distance centerline to centerline of mounting holes 46.4 cm). Feet add 1.3 cm to height.		
	9.9 kg (22.6 lbs)		
SBE 33 Deck Unit Installation Environment	 SBE 33 operates properly under following conditions: Indoor use Altitude up to 2000 meters Temperature from 5 °C to 40 °C Maximum relative humidity 80%, non-condensing Mains supply voltage ±10% 		

PDIM Dimensions and Connectors

If deploying the CTD without a water sampler, a PDIM can be used to connect the CTD to the SBE 33. Order PDIM with desired type of bulkhead connector:

- PN 90227 PDIM with XSG connectors
- PN 90473 PDIM with MCBH wet-pluggable connectors



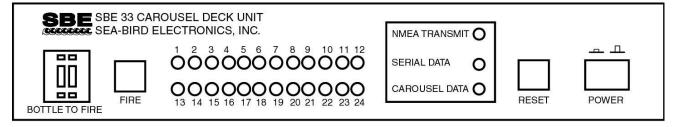
SBE 33 Front Panel

Notes:

- Bottles can also be fired from the computer using Seasave real-time data acquisition software.
- The SBE 33 was originally designed to work with the SBE 32 Carousel Water Sampler, but is also compatible with the SBE 55 ECO Water Sampler. The *Carousel Data* labels on the front and back panels also apply to operation with the SBE 55 ECO Water Sampler.

Looking at the SBE 33 front panel:

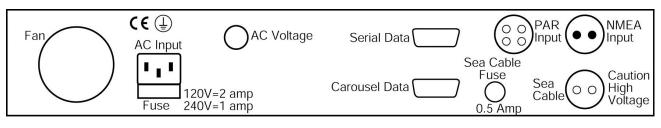
- *Bottle to Fire* pushbutton switch selects which bottle to fire when Fire button is pushed; if set to 99, SBE 33 will fire bottles in sequential order
- *Fire* button fires bottles
- *Reset* button resets system; place *Bottle to Fire* switch to 00 before pressing *Reset*
- *Power* button turns power to the SBE 33 on/off
- *LEDs* indicate if the SBE 33 is communicating with other parts of the system:
 - Red bottle number LEDs (1, 2, etc.) flash when the associated bottle is fired
 - Yellow NMEA Transmit LED flashes when a carriage return character (decimal 13) is received from the NMEA navigation device
 - Green Serial Data LED flashes when a carriage return character (decimal 13) is received from the CTD through the Water Sampler
 - Yellow Carousel Data LED flashes when a message (such as a bottle fire confirmation) is received from the Water Sampler



SBE 33 Back Panel

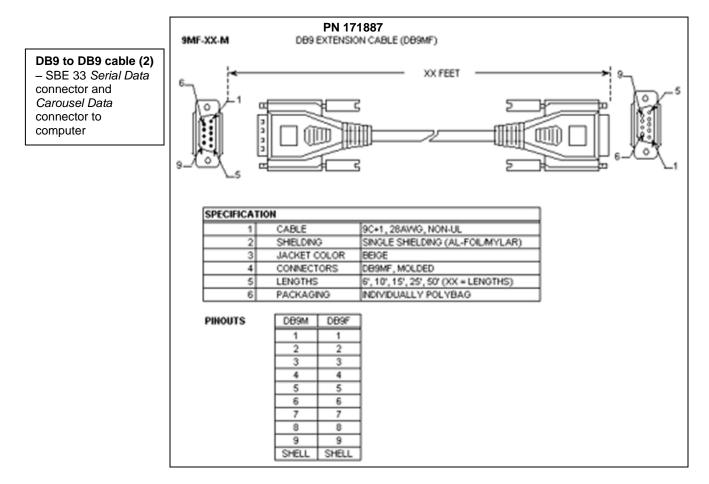
Looking at the connections to the SBE 33 back panel:

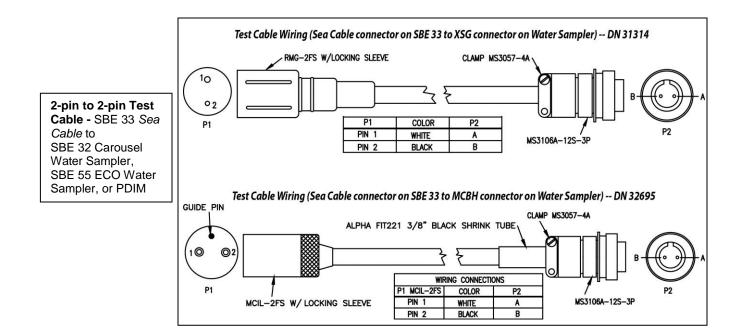
- SBE 33 communication with the computer is provided in two RS-232 channels. The *Carousel Data* channel sends commands to and receives replies from the Water Sampler. The *Serial Data* channel sends commands to and receives replies from the CTD (through the Water Sampler).
- *NMEA Input* connects to a NMEA navigation device.
- *PAR Input* connects to a Surface PAR sensor.
- *Sea Cable* connects to the Water Sampler. Fuse – 3AG, 300VDC, Fast Acting, 0.5A. Replace with Littelfuse Corp. 312.500 only.
- AC Input is 120 VAC or 240 VAC 50/60 Hz (selectable). Fuse 5x20mm, 250VAC Slow-Blow, 2 amp (for 120 V) or 1 amp (for 240 V).

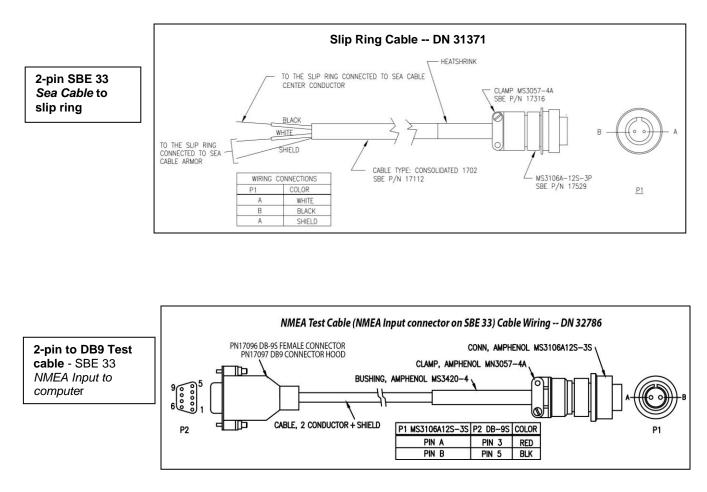


SBE 33

Cables and Wiring

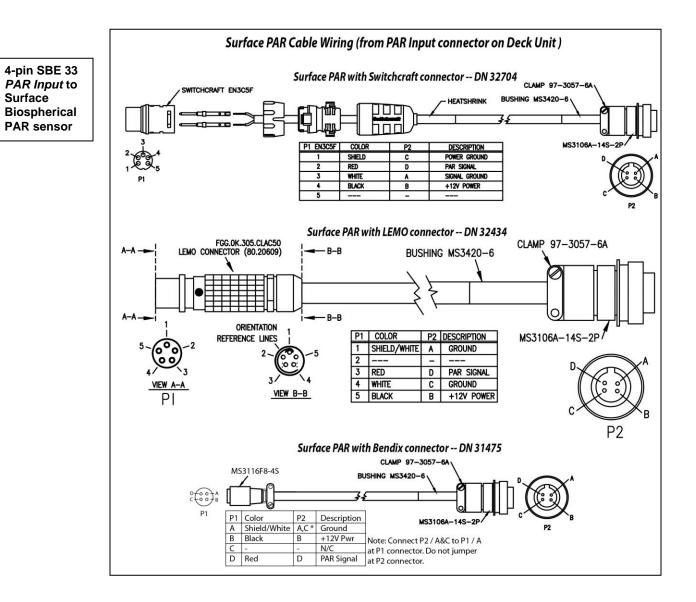




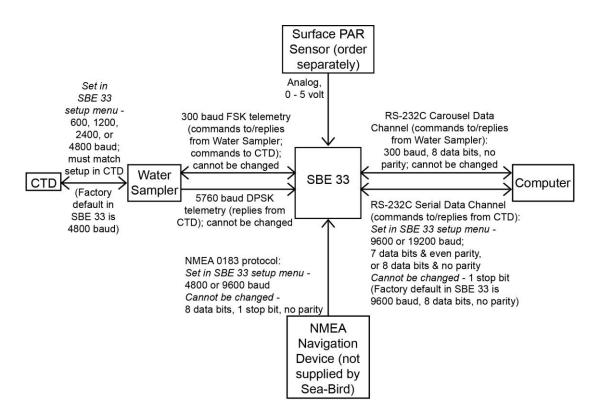


Notes:

- The Switchcraft connector on the Biospherical Surface PAR sensor is the current connector type. Biospherical sold the Surface PAR sensor with other connector types in the past. See the appropriate drawing for pinout details.
- SBE 33 can also be used with a Satlantic (Sea-Bird Scientific) Surface PAR sensor. Wiring diagram for that cable is not currently available.



System Communications



Notes:

- Abbreviations: DPSK = differential phase shift keyed, FSK = frequency shift keyed
- PDIM can be substituted for Water Sampler, when a Water Sampler is not available or needed. PDIM provides same power and CTD data interface functionality, but no water sampling capability.
- Surface PAR Sensor input: Surface PAR channel was optional in earlier versions of the SBE 33.
- Data bits and parity for Serial Data Channel between SBE 33 and computer must match data bits and parity of CTD (8 data bits and no parity for SBE 19*plus*, 19*plus* V2, 25*plus*, or 49; 7 data bits and even parity for SBE 19 or 25).
- Seasave also supports acquisition of data from a NMEA device connected directly to the computer (instead of the deck unit).
- SBE 25: If the SBE 25 is integrated with more than 4 auxiliary voltage sensors, and the SBE 33 is appending both NMEA and Surface PAR, you must set the SBE 25 real-time output rate to 4 scans/sec or less (see the SBE 25 manual for command details).
- SBE 25*plus*: If the SBE 33 is appending both NMEA and Surface PAR, you must slow down the real-time output rate by setting **SetHistoricRate=0** (see the 25*plus* manual for command details).
- SBE 49: Seasave 7.23.2 and later supports acquisition of Surface PAR data.

When sending commands to the Water Sampler to reset the system or to fire bottles, the SBE 33 sets the most significant bit low.

NMEA and Surface PAR

Notes:

- If you are not sure which NMEA messages your navigation device is sending, see Section 7: Troubleshooting for information on viewing the raw NMEA message using the SBE 33's diagnostic mode.
- SBE 25: if the SBE 25 is integrated with more than 4 auxiliary voltage sensors, and the SBE 33 is appending both NMEA and Surface PAR, you must set the SBE 25 real-time output rate to 4 scans/sec or less (see SBE 25 manual for command details).
- SBE 25*plus*: If the SBE 33 is appending both NMEA and Surface PAR, you must slow down the realtime output rate by setting **SetHistoricRate=0** (see the 25*plus* manual for command details).
- SBE 49: Seasave (real-time data acquisition software) 7.23.2 and later supports acquisition of Biospherical Surface PAR data.
- Seasave (real-time data acquisition software) 7.26.7 and later supports acquisition of Satlantic Surface PAR data.

The SBE 33 includes a NMEA 0183 interface that permits NMEA data to be merged with the CTD data. The SBE 33 is designed to decode messages that are output from devices supporting NMEA 0183 protocol. Decoded NMEA data can be appended to the end of the CTD data stream in the SBE 33 and passed to the computer for storage and/or display with the CTD data (see *Appendix I: NMEA Device Message and Data Formats*). The Yellow *NMEA Transmit* LED on the SBE 33 front panel flashes each time a NMEA message is received (should be same rate at which your NMEA device is transmitting). The SBE 33 appends the same NMEA message multiple times, until a new message is decoded.

• *Example*: A NMEA device outputs its message once every 5 seconds. The Yellow *NMEA Transmit* LED flashes every 5 seconds, and the same message is appended to each scan of CTD data within that 5 seconds.

If NMEA position data is being added to the data stream, the SBE 33 also allows for the addition of NMEA depth (for example, from a NMEA echo sounder) to the data stream.

The SBE 33 can also acquire the 0 to 5 volt output of a Surface PAR sensor, append it to the CTD data stream, and pass it to the computer for storage and/or display with the CTD data. Seasave and SBE Data Processing support the acquisition and display of data from the following sensors:

- Satlantic (Sea-Bird Scientific) Surface PAR sensor (logarithmic or linear)
- Biospherical (QSR-240, QCR-240, QSR-2200, or QCR-2200) Surface PAR sensor

- In Seaterm, use the @ character to access and exit the setup menu.
- The SBE 33 must be in Mode 1 if trying to send commands to the CTD through the SBE 33 and Water Sampler.
- To enter diagnostic modes (10 and/or 11), first put the SBE 33 in Mode 3. Then, enter a 10 or 11 at the mode selection prompt.
- To exit diagnostic modes (10 and/or 11), turn off power to the SBE 33.

The SBE 33 has three operating modes and two diagnostic modes, as well as two NMEA depth options and two Surface PAR options, and selections for setting and displaying communication parameters and start-up behavior. Mode is selected in the setup menu while communicating with the SBE 33 with Seaterm (see *Setting Up and Testing System* in *Section 3: Setting Up System*).

Туре	Mode	Description
	1: Echo only	Characters to and from CTD pass through SBE 33. No NMEA or Surface PAR data is sent. Useful for setting up CTD without needing to disconnect CTD from system and connect it directly to computer.
Operating	2: Add Lat/Lon to hex data	7 bytes of hex latitude/longitude data is added to each line of hex data from CTD. Used when position data is required with CTD data. If Options 4 and/or 6 are selected, NMEA depth data and/or Surface PAR are also appended.
Modes	3: Transmit Lat/Lon only	Data from CTD is not transmitted. Hex latitude/ longitude data is converted to ASCII text whenever a new position is received from NMEA device. Format is: LAT 47 37.51 N LON 122 09.41 W If NMEA message RMC is decoded, date and time display on next line. Format is: DDMMYY HHMMSS
	4. Add NMEA Depth to real-time Hex/Lat/Lon data	3 bytes of depth data (for example, from a NMEA echo sounder) is added to each line of hex data from CTD, after lat/lon data.
Options	5. Do not add NMEA Depth to real-time Hex/Lat/Lon data	NMEA depth data is not added.
	6. Add PAR to real- time HEX data	3 bytes of Surface PAR data is added to each line of hex data from CTD, before lat/lon/depth data.
	7. Do not add PAR to real-time HEX data	Surface PAR data is not added.
Communication	8. Change communication settings and start mode	Set/reset baud rates, data bits, and parity, NMEA baud rate, and start mode (whether SBE 33 starts in Operating Mode 1 or 2 when power applied).
Settings and Start Modes	9. Display communication settings and start mode	Display settings set up in Mode 8.
	10. Enable diagnostic level 1 (transmit raw NMEA messages)	All NMEA messages received are echoed to computer in raw form. Used to determine which NMEA messages are being received by SBE 33.
Diagnostic	 Enable diagnostic level 2 (transmit decoded NMEA messages) 	All NMEA messages received are decoded by SBE 33 and displayed on computer. If you select mode 10 and then select mode11, SBE 33 transmits raw data followed by decoded data.

Section 3: Setting Up System

This section covers:

- Installing Sea-Bird software
- Setting the baud rate in the CTD
- Setting up and testing the SBE 33
- Changing communication settings between the SBE 33 and computer
- Setting up the CTD configuration (.xmlcon or .con) file

Installing Software

Seasoft V2 was designed to work with a PC running Windows XP service pack 2 or later, Windows Vista, or Windows 7.

If not already installed, install Sea-Bird software programs on your computer using the supplied software CD.

1. Insert the CD in your CD drive.

Notes:

- Help files provide detailed information on the software.
- NMEATest, a NMEA navigation device simulation program, is part of the SBE Data Processing installation.
- Separate software manuals on CD-ROM contain detailed information on Seasave and SBE Data Processing.
- Sea-Bird supplies the current version of our software when you purchase an instrument. As software revisions occur, we post the revised software on our website. See our website for the latest software version number, a description of the software changes, and instructions for downloading the software.
- Install software: Double click on SeasoftV2.exe. Follow the dialog box directions to install the software. The installation program allows you to install the desired components. Install all the components, or just install Seaterm (terminal program), SeatermV2 (for use when directly communicating with an SBE 19*plus* V2 or 25*plus*), Seasave V7 (real-time data acquisition), and SBE Data Processing (data processing).

The default location for the software is c:\Program Files\Sea-Bird. Within that folder is a sub-directory for each program.

Setting CTD Baud Rate and Operating Parameters

Note:

The SBE 33 is factory-programmed to command the Water Sampler to communicate with the CTD at 4800 baud. The setting in the SBE 33 must match the baud rate programmed in the CTD. For the most efficient operation, keep the baud at 4800 baud if it is feasible for the CTD. Water Sampler communication with the CTD is at 600, 1200, 2400, or 4800 baud. For the most efficient operation, set the CTD baud rate to **4800 baud**.

SBE CTD	CTD Baud Rates Compatible with Water Sampler / SBE 33	CTD Firmware Version
	600 or 1200	3.0d and later, programmable
19	600, 1200, or 4800	3.1d and later (but not 4.0 series), programmable
	600, 1200, 2400, or 4800	Prior to 3.0d, contact Sea-Bird for instructions on changing baud rate if necessary
19plus or 19plus V2	1200, 2400, or 4800	All versions, programmable
	600, 1200, or 4800	3.0K and later, programmable
25	600, 1200, 2400, or 4800	Prior to 3.0K, contact Sea-Bird for instructions on changing baud rate if necessary
25plus	600, 1200, 2400, or 4800	All versions, programmable
49	1200, 2400, or 4800	All versions, programmable

The baud rate for Water Sampler communication with the CTD must be set in both the CTD and in the SBE 33.

Note:

SBE 19*plus* V2 and 25*plus* use a different terminal program; see *SBE* 19*plus* V2 or 25*plus* below.

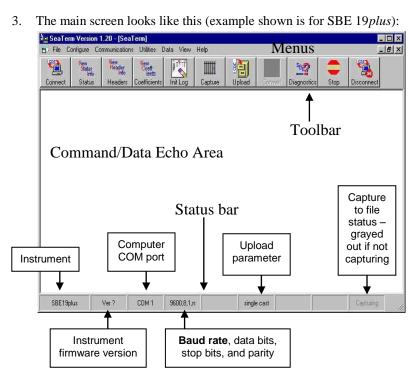
SBE 19, 19plus (not 19plus V2), 25 (not 25plus), or 49

Set (if programmable) and/or verify the CTD baud rate, and establish CTD operating parameters:

- 1. **Connect the CTD directly to the computer** (not through the SBE 33 and Water Sampler), using the data I/O cable supplied with the CTD.
- 2. Double click on **Seaterm.exe**. If this is the first time the program is used, the setup dialog box may appear:

🖷 SeaTerm Setu	p	×
was not found in	e enter the follow	ing
review the confi your instrument	To complete setu guration setting fo by selecting your from the Configure	Я
Instrument Type	SBE19plus	•
COM Port	1	•
	ОК	

Select the CTD and the computer COM port for communication with the CTD. Click OK.



- 4. In the Configure menu, select the appropriate CTD.
- 5. In the dialog box, click the COM settings tab. Select the firmware version, COM port, baud rate, data bits, and parity (see the CTD's configuration sheet). Click OK to save the settings and exit the dialog box.
- 6. In the Communications menu, select *Options / Cycle baud when connecting*.
- Click Connect on the Toolbar. Seaterm tries to connect at the baud set in Step 5. If it cannot, it cycles through all other possible baud rates to try to connect. An S> prompt shows that communication has been established.
- 8. Look at the connection baud rate in the Status bar. If this is not a baud that can be used with the Water Sampler (600, 1200, 2400, or 4800), change the baud in the CTD. The command to change the baud is given below for CTDs with programmable baud (contact Sea-Bird for instructions on older CTDs):
 - SBE 19 Send SBn, where n =1 (600 baud), 2 (1200 baud), or
 6 (4800 baud for firmware version 3.1d and above in the 3.0 series; not applicable to the 4.0 series).
 - SBE 19*plus* or 49 Send **Baud=x**, where x =1200, 2400, or 4800.
 - SBE 25 Send **SRx**, where x=1 (600 baud), 2 (1200 baud), or 4 (4800).
- 9. Click Connect on the Toolbar again; verify that the Status bar shows the new baud rate. Record the baud rate you must also set the CTD baud rate in the SBE 33 (see *Setting Up and Testing System*).
- 10. Establish other CTD setup and logging parameters (see CTD manual). Note the following requirements for use with the SBE 33:
 - SBE 19*plus* Set **OutputFormat=0** (raw hex).
 - SBE 49 Set **OutputFormat=0** (raw hex). For typical use, set **AutoRun=Y** so the SBE 49 starts sampling automatically when power is applied.
- 11. Send **QS** to put the CTD in quiescent (sleep) state (not applicable to SBE 49).

Notes:

- The SBE 33's factory-default setup commands the Water Sampler to communicate with the CTD at 4800 baud. The setting in the SBE 33 must match the baud rate programmed in the CTD.
 For the most efficient operation, keep the baud at 4800 baud if it is feasible for the CTD. See Setting Up and Testing System.
- Once all baud rates are set, you can also communicate with and change the setup of the CTD through the SBE 33 and Water Sampler using Seaterm. See Setting Up and Testing System.

25, or 49 above.

The other CTDs that are compatible

terminal program; see SBE 19, 19plus,

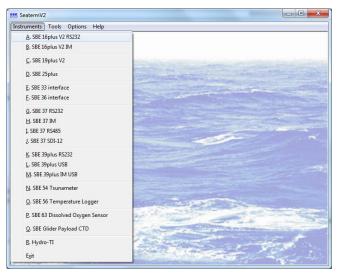
with the SBE 33 use a different

Note:

SBE 19plus V2 or 25plus

The SBE 19*plus* V2 and 25*plus* use a different terminal program than the older CTDs. Set and/or verify the CTD baud rate, and establish CTD operating parameters:

- 1. **Connect the CTD directly to the computer** (not through the SBE 33 and Water Sampler), using the data I/O cable supplied with the CTD.
- 2. Double click on SeatermV2.exe; SeatermV2 opens.



- 3. Select your CTD in the Instruments menu; Seaterm232 opens.
- 4. Follow the instructions in the software Help for connecting to the CTD.

5. Look at the connection baud rate in the title bar of the Command/Data Echo Area. If this is not a baud that can be used with the Water Sampler (≤ 4800):

- A. Change the baud in the CTD:
 - SBE 19*plus* V2: **BaudRate=x**, where x = 1200, 2400, or 4800.
 - SBE 25*plus*: **SetBaudConsole=x**, where x = 600, 1200, 2400, or 4800.
- B. Reconnect to the CTD at the new baud rate (see the software Help for details); verify that the title bar of the Command/Data Echo area shows the new baud rate.
- C. Record the baud; you must also set the CTD baud rate in the SBE 33 (see *Setting Up and Testing System*).
- 6. Establish other CTD setup and logging parameters (see CTD manual). Note the following requirements for use with the SBE 33:
 - SBE 19plus V2: Set OutputFormat=0.
 - SBE 25*plus*: Set **SetOutputFormat=0**.
- 7. Send **QS** to put the CTD in quiescent (sleep) state.

Notes:

• The SBE 33's factory-default setup commands the Water Sampler to communicate with the CTD at 4800 baud. The setting in the SBE 33 must match the baud rate programmed in the CTD. For the most efficient operation, keep the baud at 4800 baud. See Setting Up and Testing System.

• Once all baud rates are set, you can also communicate with and change the setup of the CTD **through** the SBE 33 and Water Sampler using Seaterm. See Setting Up and Testing System.

Setting Up and Testing System

Notes:

- You can also launch Seaterm from SeatermV2; you may find this useful when using the SBE 33 with a CTD that uses SeatermV2 (e.g., 19*plus* V2 or 25*plus*). In SeatermV2's Instruments menu, select SBE 33 interface; Seaterm opens. The remaining instructions (Step 2 and higher) are unchanged.
- The SBE 33 must be connected to the Water Sampler to setup and test the system. If it is not connected, noise on the open Sea Cable connector will interfere with communication with the SBE 33.

Notes:

- If the communication settings you set in Seaterm's Configure menu do not match the communication settings in the SBE 33 for communication between the SBE 33 and computer (factory default 9600 baud, 8 data bits, no parity), the display will show garbage characters. If this happens, go to Changing Communication Settings between SBE 33 and Computer below before proceeding.
- If in the setup menu and no user input is received within 60 seconds, the SBE 33 times out and exits the setup menu. Re-enter the setup menu by typing @.
- If NMEA depth is enabled (using a NMEA depth device as well as a NMEA position device) and/or Surface PAR is enabled, the description for Start mode changes to include NMEA Depth and PAR, as applicable:

start mode = Add
Lat/Lon/Depth/PAR to the realtime HEX data

- 1. Double click on seaterm.exe; Seaterm opens.
- 2. In Seaterm's Configure menu, select the SBE 33.
 - A. In the Configuration Options dialog box, click on the COM Settings tab and set the COM Settings:
 - Comm Port for connection to SBE 33 (1 through 10 as applicable)
 - Baud rate between SBE 33 and computer 9600 or 19200 (factory set to 9600)
 - Data bits and parity -SBE 19plus, 19plus V2, 25plus, or 49 - 8 data bits, no parity. SBE 19 or 25 - 7 data bits, even parity.

Click *OK* to save the settings and exit the dialog box.

3. Turn on power to the SBE 33. The SBE 33 status message displays in Seaterm:

```
SBE 33/36 Deck Unit V3.0 setup:
PC baud rate = 9600
CTD baud rate = 4800
8 data bits, no parity
NMEA baud rate = 4800
NMEA messages decoded = GGA, GLL, RMA, RMC, TRF, DBT, DPT
Surface PAR disabled
NMEA depth disabled
start mode = echo characters to and from the instrument
Press @ to change the 33/36 Deck Unit setup
```

Looking at selected lines:

Text	Description		
SBE 33/36	Both the SBE 33 and SBE 36 use the same setup procedure.		
PC baud rate	Baud for communication between computer and SBE 33's <i>Serial Data</i> channel - 9600 or 19200 (factory default 9600).		
CTD baud rate	Baud for communication between CTD and Water Sampler– 600, 1200, 2400, or 4800 (factory default 4800). Upon power-up, the SBE 33 reads this setting and automatically sends a command to the Water Sampler to set its baud rate. For the most efficient operation, keep the baud rate at 4800 baud if it is feasible for the CTD. Baud rate must be set in both the SBE 33 and in the CTD.		
8 data bits, no parity	Data bits and parity for communication between computer and SBE 33's <i>Serial Data</i> channel – set to 8 data bits and no parity for SBE 19 <i>plus</i> , 19 <i>plus</i> V2, 25 <i>plus</i> , or 49 (factory default), or 7 data bits and even parity for SBE 19 or 25. Must match data bits and parity of CTD.		
NMEA baud rate	Baud for communication between SBE 33 and NMEA device, factory set in SBE 33 to 4800 (must match NMEA device).		
NMEA messages decoded	Output from NMEA device must match one of these messages.		
Start modeDefines default behavior on power-up. Echo characters to and from the instrument (factory default) puts SBE 33 in Mode 1 on power-up, allowing system to communicate with CTD, so CTD can be set up through SBE 33. Add Lat/Lon to the real-time HEX data puts SBE 33 in Mode 2 on power- up, allowing system to start acquiring Hex and NMEA position data (and NMEA depth and/or Surface PAR, as applicable).			

Note:

If NMEA depth is enabled (using a NMEA depth device as well as a NMEA position device) and/or Surface PAR is enabled, the description for mode 2 changes to include NMEA Depth and/or PAR, as applicable: 2. Add Lat/Lon/Depth/PAR to the real-time HEX data from the instrument

Note:

The communication and start mode settings were also shown in the status message that appeared when you turned on power to the SBE 33; see Step 3 above.

Notes:

- CTD baud rate must be less than or equal to PC baud rate.
- NMEA baud rate is 4800 or 9600.
- Parity selection also affects the communication data bits: even parity = 7 data bits, no parity = 8 data bits.
- Changing *PC baud rate* or *parity* disrupts communications, because they must match the settings in Seaterm's Configure menu. See *Changing Communication Settings between SBE 33 and Computer* below for changing settings and reestablishing communications.
- If NMEA depth is enabled (using a NMEA depth device as well as a NMEA position device) and/or Surface PAR is enabled, the query for Start Mode changes to include NMEA Depth and/or PAR, as applicable: new value = echo or add Lat/Lon/Depth/PAR

4. Type @ to access the setup menu. The display looks like this:

```
SBE 33/36 Deck Unit set up menu:
Modes:
1. Echo characters to and from the instrument
2. Add Lat/Lon to the real-time HEX data from the instrument
3. Transmit Lat/Lon only
Options:
4. Add NMEA Depth to the real-time HEX/Lat/Lon data
5. Do not add NMEA Depth to the real-time HEX/Lat/Lon data
6. Add PAR to the real-time HEX data
7. Do not add PAR to the real-time HEX data
Communications:
8. Change communication settings and start mode
9. Display communication settings and start mode
Diagnostics:
10. enable diagnostic level 1
11. enable diagnostic level 2
the current mode = 1. Echo characters to and from the
instrument
enter 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, or 11 followed by Enter,
or press @ to exit the set up menu
selection =
```

5. To view the current communication and start mode settings, type 9 and press the Enter key. The display looks like this:

```
PC baud rate = 9600

CTD baud rate = 4800

8 data bits, no parity

NMEA baud rate = 4800

NMEA messages decoded = GGA, GLL, RMA, RMC, TRF, DBT, DPT

Surface PAR disabled

NMEA depth disabled

start mode = Echo characters to and from the instrument
```

If the *CTD baud rate* does not match the baud rate set in your CTD, the computer will not be able to communicate with the CTD through the SBE 33. Step 6 provides instructions for changing the CTD baud rate in the SBE 33 to match your CTD.

6. To change the current communication settings and/or start mode settings, type 8 and press the Enter key. The display looks like this:

```
      PC baud rate = X, new value =
      (type desired value, press Enter)

      CTD baud rate = X, new value =
      (type desired value. press Enter)

      parity = X, new value = even parity or no parity [e/n]
      (type desired value, press Enter)

      NMEA baud rate = X, new value =
      (type desired value, press Enter)

      Start mode = X, new value = echo or add Lat/Lon [e/a]
      (type e or a, press Enter)
```

The display then shows your new selections. Type @ to return to the setup menu.

- 7. Type *1* and press the Enter key to put the SBE 33 in mode 1 (*echo characters to and from the instrument*), which is the mode required for communicating with the CTD (i.e., sending CTD setup commands).
- 8. Type @ to exit the setup menu.
- Click Connect on the Toolbar (or press the Enter key several times) to establish communication with the CTD (through the SBE 33). The system should respond with an S> prompt.
- 10. Click Status on the Toolbar to send **DS** and display CTD status. If the status displays and is correct, the system is connected properly.
- 11. If desired, send setup commands to the CTD.

- 12. Send **QS** to put the CTD in quiescent (sleep) state (not applicable to SBE 49).
- 13. If using the SBE 33 with a NMEA device: Type @ to return to the setup menu. Type *3* and press the Enter key to switch to mode 3. The display looks like this:

Note:

If NMEA depth is enabled (using a NMEA depth device as well as a NMEA position device) and/or Surface PAR is enabled, the description for mode 2 changes to include NMEA Depth and/or PAR, as applicable: 2. Add Lat/Lon/Depth/PAR to the real-time HEX data from the instrument

Note:

NMEA depth data will not appear in Mode 3. If using both a NMEA navigation device and a NMEA depth device, go to Step 15.

Note: To exit diagnostic mode, turn off power to the SBE 33. SBE 33/36 Deck Unit set up menu: Modes: 1. Echo characters to and from the instrument 2. Add Lat/Lon to the real-time HEX data from the instrument 3. Transmit Lat/Lon only Options: 4. Add NMEA Depth to the real-time HEX/Lat/Lon data 5. Do not add NMEA Depth to the real-time HEX/Lat/Lon data 6. Add PAR to the real-time HEX data 7. Do not add PAR to the real-time HEX data Communications: 8. Change communication settings and start mode 9. Display communication settings and start mode Diagnostics: 10. enable diagnostic level 1 11. enable diagnostic level 2 the current mode = 3. Transmit Lat/Lon only

enter 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, or 11 followed by Enter, or press ${\tt @}$ to exit the set up menu

selection =

Go to **Step 14** to verify proper operation if the SBE 33 is used with a NMEA navigation (position) device.

Go to **Step 15** to verify proper operation if the SBE 33 is used with **both** a NMEA navigation (position) device **and** a NMEA depth device.

14. If using the SBE 33 with a NMEA navigation (position) device:

Type @ to exit the setup menu. You should begin seeing NMEA data display in Seaterm. Each time NMEA data is received, the yellow *NMEA Transmit* LED on the SBE 33 should flash.

- If NMEA data does not appear, verify that the SBE 33 is connected to the NMEA device and that the proper cable is used.
- See Section 7: Troubleshooting for additional instructions if needed.
- 15. If using the SBE 33 with a NMEA navigation (position) device *and* a NMEA depth device: While in mode 3, type *10* and press the Enter key to switch to mode 10. Mode 10 is a diagnostic mode that passes all raw NMEA characters received to the screen. The response indicates:

the current mode = 3. Transmit Lat/Lon/Depth only diagnostic level 1 enabled.

Type @ to exit the menu. You should begin seeing **raw** NMEA messages display in Seaterm. Typical RMC and DPT messages are:

\$LGRMC,123113.21,A,3625.12,N,12121.34,W,1.2,4.5,231294,1.2,a*45<CR><LF> \$SDDPT,0005.4,0000.0*56<CR><LF>

See Appendix I: NMEA Device Message and Data Formats for a description of all the NMEA messages the SBE 33 can decode.

- If NMEA data does not appear, verify that the SBE 33 is connected to the NMEA device and that the proper cable is used.
- See Section 7: Troubleshooting for additional instructions if needed.
- 16. Turn off power to the SBE 33.

Changing Communication Settings between SBE 33 and Computer

The SBE 33 factory defaults (9600 PC baud, 4800 CTD baud, 8 data bits, no parity) are compatible with our newer instruments (SBE 19*plus*, 19*plus* V2, 25*plus*, 49). If communication settings in Seaterm's Configure menu do not match the settings in the SBE 33, the display shows *garbage* characters when you power up the SBE 33. This happens most often when using the SBE 33 for the first time with an SBE 19 or 25, which require 7 data bits and even parity.

The procedure below applies to using an SBE 19 or 25 with an SBE 33 set at factory defaults. **Once you change communication settings in the SBE 33, it will retain the new settings, even if you remove power.**

- 1. In Seaterm's Configure menu, select the **SBE 19plus**, regardless of which CTD you are using. This allows you to establish communications using the SBE 33 defaults, so that you can then change the communications settings to match your CTD.
- 2. In the Configuration Options dialog box, click on the COM Settings tab. Set the baud rate to 9600, data bits to 8, and parity to none.
- 3. In the Communications menu, select *Send 5 second break*.
- 4. Wait at least 10 seconds. Turn power to the SBE 33 off and then on again. The display in Seaterm should look like this:

```
SBE 33/36 Deck Unit V3.0 setup:
PC baud rate = 9600
CTD baud rate = 4800
8 data bits, no parity
NMEA baud rate = 4800
NMEA messages decoded = GGA, GLL, RMA, RMC, TRF, DBT, DPT
Surface PAR disabled
NMEA depth disabled
start mode = echo characters to and from the instrument
Press @ to change the 33/36 Deck Unit setup
```

5. Type @ to change the SBE 33 setup. Type 8 and press the Enter key to change the communication settings in the SBE 33 to those required for use with your CTD (SBE 19 or 25 – 7 data bits and even parity; SBE 19*plus*, 19*plus* V2, 25*plus*, or 49 - 8 data bits and no parity; see CTD configuration sheet for CTD baud rate). The display looks like this:

```
PC baud rate = X, new value =(type desired value, press Enter)CTD baud rate = X, new value =(type desired value, press Enter)parity = X, new value = even parity or no parity [e/n](type e or n, press Enter)NMEA baud rate = X, new value =(type desired value, press Enter)Start mode = X, new value = echo or add Lat/Lon [e/a](type e or a, press Enter)
```

The display then shows your new selections. Type @ to return to the setup menu.

- In the Configure menu, select the actual CTD you are using (for 19*plus* V2 or 25*plus*, select SBE 19plus). On the COM Settings tab, select settings to match the settings you input to the SBE 33 in Step 5. Click *OK* to save the settings and exit the dialog box.
- 7. Turn power to the SBE 33 off and then on again. The display in Seaterm should look like this if you set it up for an SBE 19 or 25:

```
SBE 33/36 Deck Unit V3.0 setup:
PC baud rate = 9600
CTD baud rate = 4800
7 data bits, even parity
NMEA baud rate = 4800
NMEA messages decoded = GGA, GLL, RMA, RMC, TRF, DBT, DPT
Surface PAR disabled
NMEA depth disabled
start mode = echo characters to and from the instrument
Press @ to change the 33/36 Deck Unit setup
```

8. Continue testing, starting at Step 8 in Setting Up and Testing System above.

Note:

Send 5 second break resets the communication settings in the SBE 33 to factory defaults:

- PC baud rate 9600
- CTD baud rate 4800
- 8 data bits, no parity
- NMEA baud rate 4800

Notes:

- CTD baud rate must be less than or equal to PC baud rate.
- NMEA baud rate is 4800 or 9600.
- Parity selection also affects the communication data bits: even parity = 7 data bits, no parity = 8 data bits.

 If NMEA depth is enabled (using a NMEA depth device as well as a NMEA position device) and/or Surface PAR is enabled, the query for Start Mode changes to include NMEA Depth and/or PAR, as applicable:

new value = echo or add Lat/Lon/Depth/PAR

Checking CTD Configuration (.xmlcon or .con) File in Seasave

Notes:

- Seasave and SBE Data Processing versions 7.20 introduced .xmlcon files (in XML format). Versions 7.20 and later allow you to open a .con or .xmlcon file, and to save it to a .con or .xmlcon file. Seasave and SBE Data Processing use the same configuration file.
- A new or recalibrated CTD ships with a configuration file that reflects the current configuration as we know it. The file is named with the CTD serial number, followed by a .xmlcon extension. For example, for a CTD with serial number 2375, Sea-Bird names the file 2375.xmlcon. You may rename the file (but not the extension) if desired; this will not affect the results.

Seasave, our real-time data acquisition and display program, requires a configuration file, which defines the CTD - auxiliary sensors integrated with the CTD, and channels, serial numbers, calibration dates, and coefficients for all the integrated sensors (conductivity, temperature, and pressure as well as auxiliary sensors). Seasave (and our data processing software) uses the information in the configuration file to interpret and process the raw data. If the configuration file does not match the actual instrument configuration, the software will not be able to interpret and process the data correctly.

The configuration file must indicate if NMEA and/or PAR data is being added to the CTD data. The configuration file setup overrides the programmed settings in the SBE 33. In other words, real-time transmission via Seasave of NMEA position data, NMEA depth data, and/or Surface PAR data is dependent on the configuration file settings, not on the SBE 33 settings.

To verify the contents of the .xmlcon or .con configuration file:

- 1. Double click on Seasave.exe.
- 2. Click Configure Inputs. On the Instrument Configuration tab, click *Open*. In the dialog box, select the .xmlcon or .con file and click Open.
- 3. The configuration information appears on the Instrument Configuration tab. Verify that the sensors match those on your instrument, and that auxiliary sensors are assigned to the correct channels. Click Modify to bring up a dialog box (example shown below is for SBE 19*plus*) to change the configuration and/or to view / modify calibration coefficients.

	onfiguration for the SBE 19plus Seacat CTD	x
	Configuration file opened: None	
	Pressure sensor type Strain Gauge	
	External voltage channels 4 Channel/Sensor table	
NMEA - Select if NMEA navigation	Mode Profile	
device used, and select whether NME/ device is connected directly to Deck	Sample interval seconds 10	
Unit or to computer. You can also append NMEA depth data (3 bytes)	Scans to average	
and NMEA time data (4 bytes) after Lat/Lon data. Seasave adds current latitude, longitude, and universal time	VINEA position data added	
code to data header; appends NMEA data to every scan; and writes NMEA		
data to .nav file every time Ctrl F7 is pressed or Add to .nav File is clicked.	C NMEA device connected to PC	
Note: NMEA time can only be appended if NMEA device connected	Surface PAR voltage added Scan time added	Click a (non-shaded)
directly to computer.	Channel Sensor New	sensor and click Select
 Surface PAR - Select if Surface PAR sensor used. Seasave appends 	1. Count Temperature Shaded sensors	to pick a different sensor
Surface PAR data to every scan. Adds	2. Frequency Conductivity Cannot be removed Open	for that channel. A dialog
2 channels to Channel/Sensor table.	3. Count Pressure, Strain G another type of Save	appears. Select sensors
Do not increase External voltage channels to reflect this; External	4. A/D voltage 0 Oxygen, SBE 43 sensor. All others	after number of voltage
voltage channels reflects only external	5. A/D voltage 1 pH are optional.	channels have been
voltages going directly to CTD from	6. A/D voltage 2 Transmissometer, Chelsea/Seatech/Wetlab	specified above.
auxiliary sensor.	7. A/D voltage 3 Altimeter Select.	Click a sensor and click
See Application Note 47. Scan time added - Select to have	Modify	
Seasave append time (seconds since		calibration coefficients for
January 1, 1970 GMT) to each data		that sensor.
scan.	Report Help Exit Cancel	

4. Click *Save* or *Save As* to save any changes to the .xmlcon or .con file. Click Exit when done reviewing / modifying the configuration file.

Section 4: Mounting and Wiring System

This section covers:

- Cable, winch, and deck gear (not supplied by Sea-Bird)
- Mounting the Deck Unit
- Wiring the system

Cable, Winch, and Deck Gear (not supplied by Sea-Bird)

The electrical requirements of the armored cable are rather simple. Only one conductor is required (the armor is used as ground), and the total 2-way resistance (conductor plus armor) should be under 350 ohms. The mechanical requirements are most driven by the characteristics of the winch and weight of the payload to be lifted. The winch should have a level wind device that is either adjustable or pre-designed to lay the correct number or wraps across the drum; the cable diameter and drum width determine this. The winch must also be equipped with a slip ring (rotating contact) assembly (at least 2 channels). A cable breaking strength of at least 5 to 7 times the maximum payload weight is recommended for safety and cable longevity. The cable must also be terminated both mechanically and electrically at the underwater (instrument) end. Cable termination (mechanical) at the winch drum is usually addressed by the winch maker. The cable is terminated electrically to the slip ring per the slip ring manufacturer's specification.

Sea-Bird is not expert in winch and deck gear and cannot recommend a block and A-frame. From past experience and with knowledge of what other customers use, we can point out sources for typical cable solutions, and cable terminations suppliers. For links to suppliers of winches, cable, and cable termination hardware, see our website (www.seabird.com/products/third-party-equipment#CableAndWinch).

Mounting SBE 33

Detachable rack mount *ears* are provided for mounting the SBE 33 to standard 19-inch electronics bays.

Ensure that the back of the SBE 33, specifically the cooling fan and its vent, is not obstructed.

Wiring System

On the ship, cables longer than 3 meters should be installed inside an earthed metal conduit by a qualified electrician. This minimizes the potential for external signals to disrupt communication and ensures that high voltage lines (such as the sea cable) are sufficiently protected. Cables shorter than 3 meters can be used without shielding when installing or bench testing the instrument.

See *Cables and Wiring* in *Section 2: Description of SBE 33* for cable diagrams. See *Connector Mating and Maintenance* in *Section 6: Routine Maintenance* for connector mating details.

Water Sampler or PDIM to CTD

Connect the CTD's data I/O connector to the Water Sampler's CTD connector using the cable supplied with the CTD / Water Sampler.

- SBE 32 Carousel Water Sampler: the CTD connector is a 4-pin connector.
- SBE 55 ECO Water Sampler: the CTD connector is a 6-pin connector.

(if using PDIM in place of Water Sampler) Connect the CTD's data I/O connector to the PDIM's 4-pin connector using the cable supplied with the CTD / PDIM.

Sea Cable from SBE 33 to Water Sampler or PDIM

Mold the bottom end of the sea cable to the 2-pin pigtail (RMG-2FS or MCIL-2FS) supplied with the Water Sampler or PDIM. Connect positive power (+, cable inner conductor) to the small pin (black on the pigtail) and negative power (-, cable armor) to the large pin (white on the pigtail). If you inadvertently connect the power with the wrong polarity, no damage will be done, because there is a protective diode in series with the + power line. However, the system will not work until the condition is corrected. For safety reasons and for the most reliable performance, Sea-Bird strongly recommends use of the cable armor for the data and power return.

Make a secure mechanical connection between the cable armor and the Water Sampler lifting bail or (when used with the PDIM) the CTD cage lifting eye. Connect the sea cable to the Water Sampler or PDIM electronics, using care to dress the cable termination so that it will not be pinched by the shackle or clevis. Install a cotter pin or seize the shackle securely.

Terminate the sea cable leads from the winch slip rings with the supplied 2-pin connector (MS3106A12S-3P). Connect positive power (+, cable inner conductor) to pin B and negative power (-, cable armor) to Pin A. Connect to *Sea Cable* on the SBE 33 back panel.

SBE 33 to Computer

SBE 33 communication with the computer is provided in two RS-232 channels. The *Carousel Data* channel sends commands to and receives replies from the Water Sampler. The *Serial Data* channel sends commands to and receives replies from the CTD (through the Water Sampler). Connect the computer to *Carousel Data* and *Serial Data* on the SBE 33 back panel using the supplied cables.

Note:

The CTD optical isolation feature (SBE 25 - standard; SBE 19 - optional) must be disabled when the CTD is used with the Water Sampler:

- 1. Open the CTD main housing.
- 2. Solder a jumper wire across the neon bulb on the *above board*.

See the CTD manual for details on accessing the *above board* and for the board schematic.

This note is not applicable to the SBE 19*plus*, 19*plus* V2, 25*plus*, or 49.

WARNING!

Life threatening voltage (+250 VDC) is present on the sea cable when the SBE 33 is powered. This voltage persists for up to 1 minute after removing power. Verify that the SBE 33 is disconnected from the AC power source before connecting the sea cable to the SBE 33. Unplug the AC power cord and wait 1 minute after power is removed before working on the SBE 33 sea cable connector or sea cable circuits.

Note:

When the SBE 33 is used with the PDIM, the SBE 33 *Carousel Data* channel is not connected to the computer.

Some oceanographic vessels

ground circuit. If the SBE 33 is

isolate (un-ground) the AC power

being installed on a vessel with an isolated AC power ground, a secure separate ground connection must be made between the SBE 33 chassis and the ship's hull for SAFETY REASONS. Attach the hull connection to the protective earthing terminal located on the back panel of the SBE 33 using at least 20 AWG wire and a ring

WARNING!

Power to SBE 33

Verify that the SBE 33 back panel power selector switch is in the correct position for your mains power source. Connect power to the *AC Input* connector on the SBE 33 back panel using the supplied cable.

CAUTION:

terminal.

Connecting an SBE 33 set for 120 volts to a 240 volt power supply will cause severe damage to the SBE 33.

NMEA Navigation Device to SBE 33

Connect the NMEA navigation device to *NMEA Input* on the SBE 33 back panel with the supplied 2-pin connector (MS3106A12S-3S). The connector pin designations are:

SBE 33	Function
Pin A	NMEA A (signal)
Pin B	NMEA B (signal return)

Note:

NMEA and Surface PAR channels were optional in earlier versions of the SBE 33.

Note:

SBE 33 can also be used with a Satlantic (Sea-Bird Scientific) Surface PAR sensor. Wiring diagram for that cable is not currently available.

Surface PAR Sensor to SBE 33

Connect the Surface PAR sensor to *PAR Input* on the SBE 33 back panel. A 4-pin connector (MS3106A14S-2P) was supplied if a cable was not provided. The connector pin designations are:

Deck Unit	Function	Biospherical Surface PAR Sensor with Switchcraft Connector
Pin A	Signal (ground)	Pin 3
Pin B	Power (+12 volts)	Pin 4
Pin C	Power (ground) – SBE 33 with NMEA PCB Assembly 40785b/40786b or greater use pin C. All previous versions do not use pin C.	Pin 1
Pin D	Signal	Pin 2
-	-	Pin 5

Note: Biospherical sold the Surface PAR sensor with other connector types in the past. See the appropriate drawing for pinout details if your sensor does not have a Switchcraft connector.

Section 5: Operating System

This section covers:

- Acquiring real-time data and firing bottles from Seasave
- Firing bottles from the SBE 33 front panel
- Recovering the CTD and Water Sampler
- Uploading CTD data from memory
- Processing data using SBE Data Processing
- Editing raw data file

See *Wiring System* in *Section 4: Mounting and Wiring System* for wiring details.

Acquiring Real-Time Data and Firing Bottles from Seasave

Run Seasave to acquire real-time data and fire bottles. Proceed as follows:

1. Double click on Seasave.exe; SeasaveV7 opens.

- 2. Click Configure Inputs. The Configure Inputs dialog box appears.
 - A. Click the Serial Ports tab.

- *CTD Serial Port* - Select the computer port connected to the SBE 33 *Serial Data* connector (which sends commands to and receives replies from the CTD, through the Water Sampler), and the baud rate, data bits, and parity. The baud rate, data bits, and parity must agree with the SBE 33 setup (see *Setting Up and Testing System* in *Section 3: Setting Up System*).

- *Water Sampling and 911Pump Control Serial Port* - Select the computer port connected to the SBE 33 *Carousel Data* connector (which sends commands to and receives from the Water Sampler.

Notes:

with the SBE 33:

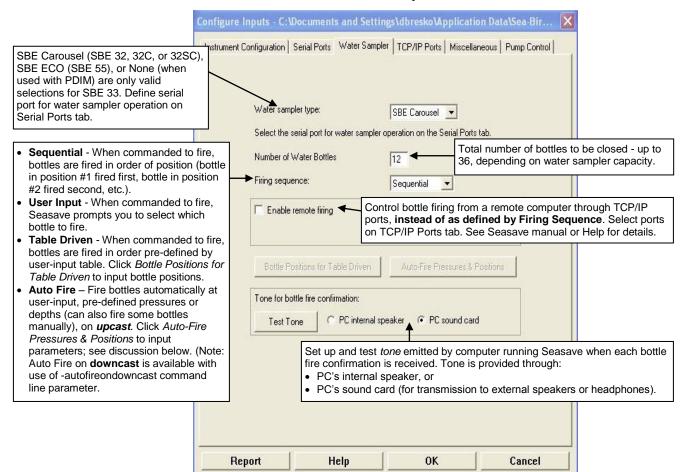
When using the SBE 49 FastCAT

 If the SBE 49 is not set to AutoRun=Y (start sampling automatically when power is applied), start sampling by sending the SBE 49 the Start command in Seaterm before you run Seasave.

 Seasave 7.23.2 and later supports acquisition of Surface PAR data

Note: When the SBE 33 is used with the PDIM, the SBE 33 *Carousel Data* channel is not connected to the computer; the water sampling COM port setting in Seasave is ignored.

B. Click the Water Sampler tab, and make the desired selections.



Perform any other desired setup in the Configure Inputs dialog box, and click OK.

- 3. Perform any other desired setup in Configure Outputs.
- 4. Perform any desired setup in the Display menu. For example, to set up the display of bottle firing parameters in a plot, click in the plot window and select *Modify*. The Plot Display dialog box appears.
 - Select *Show fire sequence* to list the bottle closure order to the right of the plot.
 - Select *Show bottle lines* to place horizontal lines in the plot to indicate data associated with closures. Select line label, style and color.

5. In the Real-Time Data menu, select *Start*. The dialog box looks like this:

 Data Archiving Options: Begin archiving data immediately to store raw (frequencies and voltages) real-time data as soon as Start button is clicked and communication is established. Begin archiving data when 'Start Archiving' command is sent to control when data begins to be written to file. This allows you to eliminate scans associated with deploying CTD from ship deck and soaking instrument near surface (alternatively, remove these scans later in SBE Data Processing). If you make this selection, when you click Start button and communication is established, a dialog box with Start Archiving button appears. Click this button when ready to begin saving scans to file, or select Start Archiving in Real-Time Data menu. Do not archive data for this cast to not save data to a file. Real-time data will etill appears in displaya 	Start Real-Time Data Acquisition Data Archiving Options Begin archiving data immediately Begin archiving data when 'Start Archiving' command is sent Do not archive data for this cast Output data [.HEX] file 	
time data will still appear in displays.	C:\Documents and Settings\dbresko	
Configuration Options : Currently selected instrument configuration (.xmlcon or .con) file is shown, containing information on number and type of sensors interfacing with CTD, calibration coefficients, and	Select Output Data File Name	Click Select Output Data File Name. Save Archived Data As dialog box appears; browse to
inclusion of NMEA and/or Surface PAR data with CTD output. To modify input configuration (.xmlcon or .con file, serial ports, water	Configuration Options	desired file location, enter desired file name, and click Save.
sampler, TCP/IP ports, and/or miscellaneous), click Configure Inputs. To modify outputs (serial data output, shared file output, mark variables, TCP/IP output, TCP/IP ports, SBE 14 remote display, PC	Instrument configuration [.xmlcon or .con] file: (to change select Configure Inputs)	
alarms, header form, and/or diagnostics), click Configure Outputs.	C:\Documents and Settings\dbresko\My Documents\19plustest.xmlcon	
Timeout in seconds at startup: Time allowed before first data scan is received from instrument. Seasave will <i>time out</i> and stop	Configure Inputs	Configure Outputs
attempting to acquire data if data is not received from instrument within this time period.	Timeout in seconds at startup	60
• Timeout in seconds between scans: Maximum gap allowed between scans after first data scan is received from instrument. Seasave will <i>time out</i> and stop attempting to acquire data if data is not received from instrument within this time period (for example, if	Timeout in seconds between scans	20
a shark bites cable and interrupts data acquisition, Seasave stops attempting to acquire data after this gap).	Reset deck unit to state 1 when a	equisition stops
Appears in dialog box if .xmlcon or con file indicates that NMEA data is added through deck unit. If selected, Seasave resets SBE 33 to State 1 when acquisition stops. State 1 is Echo only mode (no NMEA or Surface PAR data is sent), and is useful for setting up CTD.	Report Help	Start Exit Cancel

- 6. In the Start Real-Time Data Acquisition dialog box, click Start.
 - A. If you selected *Begin archiving data immediately* or *Begin archiving data when 'Start Archiving' command is sent* above, and selected *Prompt for Header Information* in the Header Form setup (Configure Outputs), the Header Information dialog box appears. Fill in the desired header and click OK.
 - B. If you set up a water sampler in Configure Inputs, Seasave sends a Reset command to the water sampler (equivalent to pushing the Reset button on the SBE 33), and waits up to 60 seconds for confirmation. If confirmation is not received, verify that:
 - Deck Unit power is on.
 - There are connections between the computer ports and Deck Unit CTD communications and water sampler channels.
 - The communication settings and COM Ports selected on the CTD Serial Port and Water Sampler tabs in Configure Inputs are correct.
 - C. If you selected *NMEA position data added* in the .xmlcon or .con file, Seasave initializes NMEA communications. Seasave automatically sends a command to put the SBE 33 in Mode 1 (do not transmit NMEA data) or Mode 2 (append NMEA and/or Surface PAR data to CTD data), depending on the settings in the configuration file.

- D. If you selected *Check Scan Length* in the Options menu, Seasave checks the .xmlcon or .con file to verify that the scan length defined by the configuration file matches the CTD (i.e., number of sensors and inclusion of NMEA and/or Surface PAR is as defined in the file). If a *Scan length error* appears, verify that:
 - You are using the correct .xmlcon or .con configuration file.
 - The configuration file has been updated as necessary if you added or deleted sensors, added or deleted NMEA, etc.
- E. Seasave sends a message:
 - SBE 19, 19plus, 19plus V2, 25, or 25plus: Seasave message is *Please turn on the ...using the magnetic switch*. If you have already started logging data, ignore the message; otherwise, move the switch to the On position. For the SBE 19, there may be a wait of up to 1 minute before data appears; for the other CTDs, data starts appearing in a few seconds.
 - SBE 49: Seasave message is *Waiting for data* Data starts appearing in a few seconds.

Seasave *times out* if data is not received within *Timeout in seconds at startup*.

- F. Real-time data then starts appearing in the screen displays.
- 7. To fire a bottle from Seasave, do one of the following:
 - Press Ctrl F3, or
 - In the Real-Time Control menu, select *Fire Bottle Control*. The *Bottle Fire* dialog box appears (you can leave this open throughout the cast). If you selected Sequential or Table driven in the Water Sampler setup (Step 2B), the Bottle Fire dialog box displays the number of the next bottle to be fired. If you selected User Input in the Water Sampler setup, select the bottle you want to fire next. When desired, click Fire Bottle.

When Seasave receives a bottle fired confirmation from the Water Sampler, it writes a line to an output file (same filename as the data file) with a .bl extension. The .bl file contains the bottle firing sequence number, bottle position, date, time, and beginning and ending scan number (to provide 1.5 seconds of scans) for the fired bottle.

- 8. To stop logging and real-time data acquisition:
 - A. For an instrument that was started by movement of a switch (such as SBE 19, 19*plus*, 19*plus* V2, 25, or 25*plus*), move the switch to the off position.
 - B. In the Real-Time Data menu, select Stop.
 - C. For an instrument that was started by command, close Seasave. Open Seaterm, establish communications with the CTD, and send the appropriate command to stop sampling. Then send the command to put the CTD in quiescent (sleep) state (sleep state not applicable to the SBE 49).

Note:

The SBE 19 (not 19plus or 19plus V2) and 25 (not 25plus) CTD must be in quiescent (sleep) state when the magnetic switch is turned on to start logging data. If not, when the switch is turned on the CTD will not log data. A common problem is that communications are established with the CTD using Seaterm, and then Seaterm is exited without putting the CTD into guiescent state with QS. When 2 minutes pass without any communication between the computer and CTD, the CTD times out and enters quiescent state automatically. To ensure that Seasave works correctly, verify that the CTD is in quiescent state or is already logging data when Seasave is started.

Note:

See the SBE Data Processing manual and/or help files for processing data in the .bl file.

Firing Bottles from SBE 33 Front Panel

Instead of firing bottles in Seasave, you can fire bottles directly from the SBE 33 if desired. Bottles fired from the SBE 33 can be in random or sequential order, regardless of the firing sequence you input in Seasave.

Note:

See the SBE Data Processing manual and/or help files for details on processing the data.

Note:

Sea-Bird strongly recommends that you do not *mix* firing bottles from both Seasave and the SBE 33 in the same cast. That is, use only one method to fire bottles to ensure that each bottle is fired only once and in the desired order. Even though you are firing the bottles from the SBE 33, Seasave still receives a bottle fired confirmation from the Water Sampler if the SBE 33 back panel *Carousel Data* and *Serial Data* are connected to the computer. When Seasave receives the confirmation, it writes a line to an output file (same filename as the data file) with a .bl extension. The .bl file contains the bottle firing sequence number, bottle position, date, time, and beginning and ending scan number (to provide 1.5 seconds of scans) for the fired bottle.

See Acquiring Real-Time Data and Firing Bottles from Seasave above for setting up Seasave and starting and stopping real-time data acquisition. Proceed as follows for firing bottles from the SBE 33:

- 1. Reset the system before beginning to fire bottles:
 - A. Set the *Bottle to Fire* pushbutton switch to 00.
 - B. Press the *Reset* button.

2. To fire bottles in random order:

- A. Set the *Bottle to Fire* pushbutton switch to the desired bottle.
- B. Press the *Fire* button.
- C. Repeat Steps A and B for each bottle.

3. To fire bottles in sequential order:

- A. Set the *Bottle to Fire* pushbutton switch to 99.
- B. Press the Fire button. The Water Sampler will fire bottle 1.
- C. Repeat Step B to fire each bottle; the Water Sampler will fire bottles in sequential order.

Recovering CTD and Water Sampler

WARNING!

If the CTD or Water Sampler stop working while underwater, are unresponsive to commands, or show other signs of flooding or damage, carefully secure the instruments away from people until you have determined that abnormal internal pressure does not exist or has been relieved. Pressure housings may flood under pressure due to dirty or damaged o-rings, or other failed seals. When a sealed pressure housing floods at great depths and is subsequently raised to the surface, water may be trapped at the pressure at which it entered the housing, presenting a danger if the housing is opened before relieving the internal pressure. Instances of such flooding are rare. However, a housing that floods at 5000 meters depth holds an internal pressure of more than 7000 psia, and has the potential to eject the end cap with lethal force. A housing that floods at 50 meters holds an internal pressure of more than 85 psia; this force could still cause injury. See the CTD and/or Water Sampler manual for instructions on relieving pressure inside the housing.

Rinse the CTD, auxiliary sensors, and Water Sampler with fresh water.

Uploading CTD Data from Memory

Notes:

- The SBE 49 does not have a memory for storing data.
- The SBE 25*plus* does not transmit real-time data from any auxiliary serial sensors integrated with the CTD; you must upload the data from memory to access the serial sensor data.

Typically, data processing is performed on the real-time data acquired in Seasave. However, some users choose to upload the data in the CTD memory as a back-up to the real-time data. This allows for comparison of the data in memory to the real-time data, to ensure that cable problems, noise, etc. did not corrupt the real-time data.

Upload data from the CTD memory as follows:

- 1. When the cast is complete, turn the CTD switch off.
- 2. Turn power to the SBE 33 off.
- 3. Disconnect the CTD from the Water Sampler.
- 4. **Connect the CTD directly to the computer**, using the data I/O cable provided with the CTD. Follow directions in the CTD manual for uploading data.

Processing Data Using SBE Data Processing

Note:

See the SBE Data Processing manual and/or Help files.

- 1. Use SBE Data Processing's Data Conversion module to convert the **realtime** .hex raw data file and the .bl bottle log file created by Seasave to:
 - A .cnv file, with all data converted to engineering units
 - A .ros water bottle file, containing data for a user-selected range of scans before and after each bottle firing
- 2. If desired, convert the raw data file (.xml for SBE 25*plus*; .hex for all other CTDs) **uploaded** from the CTD memory to a .cnv file in SBE Data Processing's Data Conversion module, for comparison to the real-time data.
- 3. Once the data is converted: perform further processing (align, filter, remove bad data, etc.), calculate derived variables, and plot data using SBE Data Processing's other modules.

Editing Raw Data File

Sometimes users want to edit the raw data file before beginning processing, to remove data at the beginning of the file corresponding to instrument *soak* time, to remove blocks of bad data, to edit the header, or to add explanatory notes about the cast. **Editing the raw file can corrupt the data, making it impossible to perform further processing using Sea-Bird software.** Sea-Bird strongly recommends that you first convert the data to a .cnv file (using SBE Data Processing's Data Conversion module), and then use other SBE Data Processing modules to edit the .cnv file as desired.

The procedure for editing a .hex data file described below has been found to work correctly on computers running Windows 98, 2000, and NT. If the editing is not performed using this technique, SBE Data Processing may reject the edited data file and give you an error message.

- 1. Make a back-up copy of your .hex data file before you begin.
- 2. Run WordPad.
- 3. In the File menu, select Open. The Open dialog box appears. For *Files of type*, select *All Documents* (*.*). Browse to the desired .hex data file and click Open.
- Edit the file as desired, inserting any new header lines after the System Upload Time line. Note that all header lines must begin with an asterisk (*), and *END* indicates the end of the header. An example is shown below (for an SBE 21), with the added lines in bold:

```
* Sea-Bird SBE 21 Data File:
* FileName = C:\Odis\SAT2-ODIS\oct14-19\oc15 99.hex
* Software Version Seasave Win32 v1.10
* Temperature SN = 2366
* Conductivity SN = 2366
* System UpLoad Time = Oct 15 1999 10:57:19
* Testing adding header lines
* Must start with an asterisk
* Place anywhere between System Upload Time & END of header
* NMEA Latitude = 30 59.70 N
* NMEA Longitude = 081 37.93 W
* NMEA UTC (Time) = Oct 15 1999 10:57:19
* Store Lat/Lon Data = Append to Every Scan and Append to .NAV
File When <Ctrl F7> is Pressed
** Ship:
              Sea-Bird
** Cruise:
               Sea-Bird Header Test
** Station:
** Latitude:
** Longitude:
*END*
```

5. In the File menu, select Save (**not** Save As). If you are running Windows 2000, the following message displays:

You are about to save the document in a Text-Only format, which will remove all formatting. Are you sure you want to do this?

Ignore the message and click Yes.

6. In the File menu, select Exit.

Note:

Although we provide this technique for editing a raw .hex file, **Sea-Bird's** strong recommendation, as described above, is to always convert the raw data file and then edit the converted file.

Section 6: Routine Maintenance

This section reviews underwater connector mating and maintenance, and cleaning the SBE 33 Deck Unit.

Connector Mating and Maintenance

Note:

See Application Note 57: Connector Care and Cable Installation.

Clean and inspect connectors, cables, and dummy plugs before every cruise, during a cruise (good practice if you have a few days of down time between casts), after every cruise, and as part of your yearly equipment maintenance. Inspect connectors that are unmated for signs of corrosion product around the pins, and for cuts, nicks or other flaws that may compromise the seal.

When remating connectors for underwater portions of the system:

- CAUTIONS:
- Do not use WD-40 or other petroleum-based lubricants, as they will damage the connectors.
- For wet-pluggable MCBH connectors: Silicone lubricants in a spray can may contain ketones, esters, ethers, alcohols, or glycols in their propellant. Do not use these sprays, as they will damage the connector.

1. Lightly lubricate the inside of the dummy plug / cable connector with silicone grease (DC-4 or equivalent).

2. **XSG / AG Connector** - Install the cable connector, aligning the raised bump on the side of the cable connector with the large pin (pin 1 - ground) on the end cap. Remove any trapped air by *burping* or gently squeezing the connector near the top and moving your fingers toward the end cap. **OR**

MCBH Connector – Install the cable connector, aligning the pins.

3. Place the locking sleeve over the dummy plug / cable connector. Tighten the locking sleeve finger tight only. Do not overtighten the locking sleeve and do not use a wrench or pliers.

Verify that a cable or dummy plug is installed for each connector on the system before deployment.

Cleaning SBE 33 Deck Unit

To clean the SBE 33:

- 1. Disconnect the power and any other cables from the back of the SBE 33.
- 2. Using a soft cotton cloth dampened with warm water, clean the exterior of the SBE 33 with gentle pressure. Use special care cleaning around any connectors, to avoid getting water into them.
- 3. Wait until the SBE 33 is completely dry before reconnecting power cables and other electrical connections.

Section 7: Troubleshooting

WARNING!

Life-threatening high voltages are present in the SBE 33 and the underwater units when power is on. These hazardous voltages persist for up to 1 minute after removal of power. To protect against electrical shock, disconnect the AC power cord from the SBE 33 and then wait a full minute before attempting service. Always disconnect the AC power cord before checking fuses. This section reviews common problems in operating the SBE 33, and provides the most likely causes and solutions.

Servicing should be performed by experienced technicians who have been trained to work with complex mechanical/electrical equipment.

For protection of the circuitry, we also recommend removing AC power and then waiting for 1 minute for supply capacitor discharge before opening housings, changing connections, removing or inserting circuit cards, or otherwise working on the equipment.

Problem 1: Unable to View Data in Seasave (Real-Time Data Acquisition program)

Note:

If *Check scan length* is enabled in Seasave's Options menu, Seasave checks the data scan length against the expected length (based on the configuration file setup), and provides a warning that there is an error. Sea-Bird recommends using this setting. **Cause/Solution 1**: If the scan length does not match the selected .xmlcon or .con configuration file (for example, the configuration file indicates that NMEA position data is added through a NMEA device connected to the computer, but you did not connect the NMEA device to the computer), **Seasave continues with real-time data acquisition (saving the raw data to a file for later processing), but does not show or plot data in the Seasave displays.** The data quality is not affected; you can correct the configuration file error in SBE Data Processing (post-processing), and process the data as required. Verify that the settings in the configuration file match the current CTD configuration - number and type of auxiliary sensors, sensors assigned to correct channels, NMEA and Surface PAR selected if applicable.

Problem 2: SBE 33 Completely Inoperable

WARNING! Use extreme caution when making these tests.

Cause/Solution 1:

If the power switch is on but the power switch pilot light is out, no other panel lights are on, and the fan is not running, either AC power has been disconnected or the main fuse has blown. Check the AC power source. Turn off the SBE 33, remove the power cable, wait 1 minute, and check the main fuse. Replace if necessary.

If the main fuse blows again, there is probably a short in the main chassis AC wiring. See the chassis wiring diagram - it may be necessary to disconnect one section after another to locate the problem.

Problem 3: Water Sampler or CTD Does Not Respond

WARNING! Use extreme caution when making these tests.

Cause/Solution 1:

There may be no voltage on the sea cable. Turn off the SBE 33, remove the power cable, and wait 1 minute. Connect a voltmeter (range set to at least 300 volts DC) to the back-panel *Sea Cable* connector. Turn on the SBE 33. The voltmeter should read 250V.

If no sea cable voltage is observed, the sea cable supply is inoperative. Turn off the SBE 33, remove the power cable, and wait 1 minute. Check the backpanel *Sea Cable Fuse*. If this fuse is blown, the sea cable may have been inadvertently shorted, or the Water Sampler or CTD may be malfunctioning. Check the resistance across the sea cable and correct if shorted. You can also perform a check with your water sampler and the supplied test cable; try to fire the water sampler in this manner (bypassing the actual sea cable). If the system works with the test cable, there could be problems with the sea cable and/or termination.

Problem 4: Unsupported Modem Message (FFFFFFF Unsupported modem message: xx xx xx) from Water Sampler

Cause/Solution 1:

There may be noise on the line, causing extra characters to be sent. Check the sea cable for damage (see Problem 3 above). Also check the cable between the water sampler and the CTD.

Cause/Solution 2:

The baud rate and/or serial port for water sampler control may be incorrect.

- Check the serial port setting in Seasave (Configure Inputs, Serial Ports tab, *Water Sampling and 911 Pump Control Serial Port*); this should be the port connected to the SBE 33 *Carousel Data* connector.
- Check the baud rate setting for CTD communication in Seasave (Configure Inputs, Serial Ports tab, *CTD Serial Port*); in the SBE 33 (CTD baud rate). This must match the *CTD baud rate* set in the SBE 33 (which is also the baud rate used for communication between the CTD and the Water Sampler) and the baud rate set in the CTD. For the most efficient operation, keep this baud rate at 4800 if feasible for the CTD.

Cause/Solution 3:

The Carousel may be malfunctioning and sending bad messages.

Problem 5: Yellow NMEA Transmit LED Not Flashing

Cause/Solution 1:

Wiring may be incorrect. Check cables and connections between the SBE 33, NMEA navigation device, and computer.

Cause/Solution 2:

NMEA navigation device may be set to the wrong baud rate (SBE 33 requires 4800 or 9600 baud). Reset device's baud rate.

Cause/Solution 3:

NMEA navigation device may not be transmitting data. See the device manual for setup details. To verify that it is sending data, connect an oscilloscope with ground on NMEA B (T17) and the probe on NMEA A (T16). The signal should be less than 0.5 volts between messages and have pulses greater than 4 volts for at least 0.2 milliseconds during the message.

Cause/Solution 4:

SBE 33 may not be operating properly. To verify, use the NMEA simulation program supplied with Seasoft. This program simulates a NMEA navigation device transmitting a NMEA message (see *Appendix II: NMEA Message Simulation Program*).

Problem 6: Yellow NMEA Transmit LED Flashing, but Lat/Lon Data Not Displaying

Cause/Solution 1:

NMEA device may be transmitting a NMEA message that has an unexpected format. See *Appendix I: NMEA Navigation Device Message and Data Formats* for a description of all the NMEA messages the SBE 33 can decode.

Glossary

Note:

All Sea-Bird software listed was designed to work with a computer running Windows XP service pack 2 or later, Windows Vista, or Windows 7. **NMEATest –** Sea-Bird's Windows NMEA message simulation program, which simulates NMEA messages for testing purposes (installed with SBE Data Processing).

PCB – Printed Circuit Board.

SBE Data Processing – Sea-Bird's Windows data processing software, which calculates and plots temperature, conductivity, pressure, data from auxiliary sensors, and derived variables such as salinity and sound velocity.

Scan – One data sample containing temperature, conductivity, pressure, and optional auxiliary inputs.

Seasave V7 – Sea-Bird's Windows software used to acquire, convert, and display real-time or archived raw data.

Seasoft V2– Sea-Bird's complete Windows software package, which includes software for communication, real-time data acquisition, and data analysis and display. Seasoft V2 includes **Seaterm, SeatermV2, Seasave V7, SBE Data Processing**.

Seaterm – Sea-Bird's Windows terminal program used to communicate with the SBE 33 and/or the CTD.

SeatermV2 – Windows terminal program *launcher*. Depending on the instrument selected, it launches Seaterm232 (RS-232 instruments), Seaterm485 (RS-485 instruments), or SeatermIM (inductive modem instruments).

Seaterm232 – Windows terminal program used with Sea-Bird instruments that communicate via an RS-232 interface, and that were developed or redesigned in 2006 and later. The common feature of these instruments is the ability to output status information in XML.

Safety and Electrical Symbols

Some or all of the following symbols may be used on the SBE 33:

Symbol	Description
4	Potentially hazardous voltage.
A	Hazardous! Voltage > 30 VDC may be present.
\wedge	Attention! There is a potential hazard; consult the manual before continuing.
	DC (Direct Current).
	Double insulated. The metal enclosure of the SBE 32 is isolated such that protection from electrical shock is provided through reinforced electrical insulation.
	Static awareness. Static discharge can damage part(s).
	Protective earthing terminal.

Appendix I: NMEA Navigation Device Message and Data Formats

Message Formats

Notes:

- -- represents two device-specific characters.
- x represents miscellaneous parameters that are ignored by the SBE 33.
- <CR> is carriage return.
- <LF> is line feed.
- See the table below for definitions of message parameters.
- Seasave and SBE Data Processing are compatible with NMEA depth data in the data stream. NMEA depth data can be decoded and merged with CTD data only if NMEA position data is also available.
- Seasave supports acquisition of data from a NMEA device connected to the deck unit or connected directly to the computer.

GGA - Global Positioning System Fix Data

Time, position, and fix related data for a GPS receiver. \$--GGA,hhmmss.ss,llll.ll,a,yyyyy.yy,b,x,xx,x.x,M,x.x,M,x.x,M,x.x,Xxx*hh<CR><LF>

GLL - Geographic Position - Latitude/Longitude

Latitude and Longitude of present position, time of position fix, and status. \$--GLL,llll.ll,a,yyyyy.yy,b,hhmmss.ss,A*hh<CR><LF>

RMA - Recommended Minimum Specific Loran-C Data

Position, course, and speed data provided by a LORAN-C receiver. \$--RMA,A,llll.ll,a,yyyyy.yy,b,x.x,x.x,x.x,x.x,a*hh<CR><LF>

RMC - Recommended Minimum Specific GPS/TRANSIT Data

Time, date, position, course, and speed data provided by a GPS or TRANSIT navigation receiver.

 $\label{eq:linear} \$-RMC, hhmmss.ss, A, llll.ll, a, yyyyy.yy, b, x.x, x.x, ddmmyy, x.x, a*hh <\!\!CR\!>\!\!<\!\!LF\!\!>$

TRF - TRANSIT Fix Data

Time, date, position, and information related to a TRANSIT fix. \$--TRF,hhmmss.ss,ddmmyy,llll.ll,a,yyyyy,b,x.x,x.x,x.x,x.x,A*hh<CR><LF>

DBT – Depth Below Transducer

Depth in fathoms, meters, and feet \$--DBT,xxxx.x,f,dddd.d,M,xxxx.x,F*hh<CR><LF>

DPT – Depth

Depth

\$--DPT,dddd.d,xxxx.x,xxxx.x*hh<CR><LF>

Field Type	Symbol	Definition
Status	А	Single character field: $A = Yes$, data valid, warning flag clear $V = No$, data invalid, warning flag set
Latitude	1111.11	Fixed/Variable length field: degrees minutes.decimal - 2 fixed digits of degrees, 2 fixed digits of minutes, variable number of digits for decimal-fraction of minutes. Leading zeros always included for degrees and minutes to maintain fixed length. Decimal point and associated decimal-fraction optional if full resolution not required.
	а	N or S
Longitude	ууууу.уу	Fixed/Variable length field: degrees minutes.decimal - 3 fixed digits of degrees, 2 fixed digits of minutes, variable number of digits for decimal-fraction of minutes. Leading zeros always included for degrees and minutes to maintain fixed length. Decimal point and associated decimal-fraction optional if full resolution not required.
	b	E or W
Time	hhmmss.ss	Fixed/variable length field: hours/minutes/seconds.decimal - 2 fixed digits each of hours, minutes, and seconds; variable number of digits for decimal-fraction of seconds. Leading zeros always included for hours, minutes, and seconds to maintain fixed length. Decimal point and associated decimal-fraction optional if full resolution not required.
Depth	dddd.d (see note at right)	Depth below transducer in meters. Note: Format can be dddd.d or ddd.d
Checksum	*	Optional Checksum Delimiter.
	hh	Optional Checksum Field: Absolute value calculated by exclusive OR'ing 8 data bits (no start or stop bits) of each character in message, between, but excluding \$ and *.

Data Formats

Note:

If a Surface PAR sensor is also connected to the SBE 33, the Surface PAR data (three bytes) is appended *before* the position data.

Position Data

Seven bytes of NMEA position data are appended to each scan of hex data from the instrument.

Our software calculates latitude and longitude as follows:

Latitude (deg) = (byte 1 * 65536 + byte 2 * 256 + byte 3) / 50000

Longitude (deg) = (byte 4 * 65536 + byte 5 * 256 + byte 6) / 50000

Notes:

- 1. If bit 1 in byte 7 is 1, this is a new position.
- 2. If bit 8 in byte 7 is 1, Latitude is negative.
- 3. If bit 7 in byte 7 is 1, Longitude is negative.
- 4. North latitudes are positive, south latitudes are negative.
- 5. East longitudes are positive, west longitudes are negative.

Example:

Appended position data = 2455FC5D32B141 byte 1 = 24 hex = 36 decimal byte 2 = 55 hex = 85 decimal byte 3 = FC hex = 252 decimal byte 4 = 5D hex = 93 decimal byte 5 = 32 hex = 50 decimal byte 6 = B1 hex = 177 decimal byte 7 = 41 hex = 01000001 binary This is a new position (bit 1 in byte 7 is 1). Latitude is positive (bit 8 in byte 7 is 0). Longitude is negative (bit 7 in byte 7 is 1). Latitude = (36 * 65536 + 85 * 256 + 252) / 50000 = 47.62616 degrees Longitude = (93 * 65536 + 50 * 256 + 177) / 50000 = -122.1565 degrees

Depth Data (if applicable)

Three bytes of depth data are appended to each scan of data, after the position data.

Our software calculates depth as follows:

Depth (meters) = (byte 1 * 65536 + byte 2 * 256 + byte 3) / 10

Example: Appended depth data = 0032FC byte 1 = 00 hex = 0 decimal byte 2 = 32 hex = 50 decimal byte 3 = FC hex = 252 decimal Depth = (0 * 65536 + 50 * 256 + 252) / 10 = 1305.2 meters

Appendix II: NMEA Message Simulation Program

Sea-Bird provides a NMEA message simulation program, NMEATest, as a troubleshooting aid. NMEATest, part of the Seasoft V2 package, simulates a NMEA navigation devices transmitting NMEA messages. If the system does not work with the actual NMEA navigation device, but works with NMEATest, the problem is with the interface cable from the NMEA navigation device itself.

Note:

While NMEATest can *generate* messages in only the four formats shown, it can *run* using an existing raw NMEA data file in these formats as well as TRF, DBT, and DPT.

Note:

You can also run the simulation using only one computer, if the computer has a spare COM port.

Note:

The SBE 33 must be connected to the Water Sampler to test the NMEA interface. If it is not connected, noise on the open *Sea Cable* connector will interfere with communication with the SBE 33.

NMEATest is just a simulation, and does not provide an actual data stream from an actual NMEA navigation device. The data transmission baud rate (4800 or 9600) and time between messages are user-programmable. The NMEA message format (RMA, RMC, GLL, or GGA) generated by the program is also user-programmable. Alternatively, the user can specify an existing raw NMEA data file to use for the simulation; see *Appendix 1: NMEA Navigation Device Message and Data Formats* for the required raw data format.

To execute the simulation program, a **second computer** (computer 2) is needed to emulate the NMEA navigation device. A laptop computer is adequate for this purpose. Install NMEATest on computer 2 (NMEATest is part of the SBE Data Processing installation).

Use the NMEA Interface test cable (PN 801422 - supplied with the SBE 33) to connect *NMEA Input* on the SBE 33 to the simulation computer. The simulation test cable connections are:

MS3106A12S-3S	DB-9S	Function
Pin A	Pin 3	NMEA A (signal)
Pin B	Pin 5	NMEA B (signal return)

Proceed as follows (instructions are written assuming you are using a second computer to emulate the NMEA navigation device):

- 1. On computer 1, set up Seaterm to communicate with the SBE 33 at 9600 or 19200 baud, 7 or 8 data bits, no or even parity (Steps 1 and 2 in *Setting Up and Testing System* in *Section 3: Setting Up System*).
- 2. Turn on power to the SBE 33. The SBE 33 status message displays in Seaterm:

```
SBE 33/36 Deck Unit V3.0 setup:
PC baud rate = 9600
CTD baud rate = 4800
8 data bits, no parity
NMEA baud rate = 4800
NMEA messages decoded = GGA, GLL, RMA, RMC, TRF, DBT, DPT
Surface PAR disabled
NMEA depth disabled
start mode = echo characters to and from the instrument
Press @ to change the 33/36 Deck Unit setup
```

- 3. Type @ to access the NMEA Interface menu.
- 4. Type 3 and press the Enter key to switch to mode 3.

- 5. When in mode 3:
 - A. Type *10* and press the Enter key to switch to mode 10. Mode 10 transmits all NMEA messages in raw form. The menu response indicates that the SBE 33 has *diagnostic level 1 enabled*.
 - B. Type *11* and press the Enter key to switch to mode 11. Mode 11 transmits NMEA messages in decoded form. The menu response indicates that the SBE 33 has *diagnostic level 1 enabled* and *diagnostic level 2 enabled*, so NMEA messages will be transmitted in raw form followed by decoded form.
- 6. On computer 2, double click on **nmeatest.exe** (in same directory as SBE Data Processing). The NMEATest screen appears.
- 7. On the NMEATest screen, click on the Configure menu. The Configure dialog box appears. Select:
 - NMEA message to be simulated (RMA, RMC, GLL, or GGA) or select an existing NMEA data file on your computer by clicking *Send File* and browsing to the desired file. If selecting a NMEA data file, the NMEA message must be compatible with the SBE 33 (GGA, GLL, RMA, RMC, TRF, DBT, or DPT).
 - Baud rate for transmission of simulated NMEA data to SBE 33 (4800 or 9600) –**must match SBE 33 setup**.
 - COMM port on computer 2 for transmission of NMEA data to SBE 33.
 - Message interval (time between simulated messages to be transmitted to SBE 33).

Click OK.

8. On the NMEATest screen, click Start. NMEA data should begin to display on the NMEATest screen on computer 2 and in Seaterm on computer 1. The yellow *NMEA transmit* light should flash each time the simulation program transmits a new position.

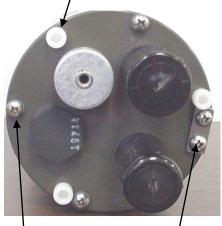
The data displayed by Seaterm should correspond to that of the simulation program (see *Appendix I: NMEA Navigation Device Message and Data Formats* for the raw and decoded NMEA message formats). If properly decoded data appears on the screen, the SBE 33 is working properly. If the system works with the simulation program but does not work when connected to the actual NMEA navigation device, the problem is with the cable from the NMEA navigation device to the SBE 33, or in the NMEA navigation device itself.

- Verify that the cable pinouts are correct, especially at the NMEA navigation device. See *Wiring System* in *Section 4: Mounting and Wiring System* and also refer to the NMEA navigation device documentation.
- If the cable is correct, verify that the NMEA navigation device is on and is configured to send data. Many NMEA navigation devices have programmable NMEA outputs and may need to be configured before they will transmit NMEA messages. Again, refer to the NMEA navigation device documentation, or contact the device's manufacturer for customer support.

Appendix III: PDIM Electronics Disassembly/Reassembly



Remove plastic hex head screws and install jackscrews in their place



Remove 4 Phillips-head screws This Phillips-head screw does not connect to housing - do not remove

Sea-Bird provides a jackscrew kit with the PDIM, to assist in removal of the connector end cap. The kit contains:

- 2 Allen wrenches
- 3 jackscrews
- 2 spare plastic socket hex-head screws

Disassembly

Remove the connector end cap and attached electronics PCB assembly as follows:

- 1. Wipe the outside of the end cap and housing dry, being careful to remove any water at the seam between them.
- 2. Remove the four Phillips-head screws securing the end cap to the housing.
- 3. Remove the three plastic hex head screws from the end cap using the larger Allen wrench. Insert the three jackscrews in these three holes in the end cap. When you begin to feel resistance, use the smaller Allen wrench to continue turning the screws. Turn each screw 1/2 turn at a time. As you turn the jackscrews, the end cap will push away from the housing. When the end cap is loosened, pull it and the PCB assembly out of the housing.
- 4. Remove any water from the O-ring mating surfaces inside the housing with a lint-free cloth or tissue.
- 5. Disconnect the Molex connector connecting the PCB assembly to the PDIM.
- 6. Remove the jackscrews from the end cap.

Note:

Before delivery, a desiccant package is inserted in the housing and the electronics chamber is filled with dry Argon gas. These measures help prevent condensation. To ensure proper functioning:

- 1. Install a new desiccant bag each time you open the electronics chamber. If a new bag is not available, see *Application Note* 71: *Desiccant Use and Regeneration* (drying).
- If possible, dry gas backfill each time you open the housing. If you cannot, wait at least 24 hours before redeploying, to allow the desiccant to remove any moisture from the housing.
 Note that opening the battery

compartment does not affect desiccation of the electronics.

Reassembly

- 1. Remove any water from the O-ring and mating surfaces with a lint-free cloth or tissue. Inspect the O-ring and mating surfaces for dirt, nicks, and cuts. Clean or replace as necessary. Apply a light coat of O-ring lubricant (Parker Super O Lube) to O-ring and mating surfaces.
- 2. Reconnect the Molex connector to the PCB assembly.
- 3. Carefully fit the PCB assembly into the housing, aligning the holes in the end cap and housing.
- 4. Reinstall the 4 Phillips-head screws to secure the end cap to the housing.
- 5. Reinstall the 3 plastic hex head screws in the end cap.

Appendix IV: Replacement Parts

Part Number	Part	Application Description	Quantity
171887	9-pin DB-9F to 9-pin DB-9M cable, 3 m (10 ft)	Connect <i>Serial Data</i> and <i>Carousel Data</i> on SBE 33 to computer COM ports	2
801422	2-pin MS3106A-12S-3S to 9-pin DB-9S NMEA Interface test cable, 1.8 m (6 ft)	Connect <i>NMEA Input</i> on SBE 33 to computer running NMEA simulation program for test purposes	1
171888	25-pin DB-25S to 9-pin DB-9P cable adapter	For use with computer with DB-25 connector	-
17015	SBE 33 power cable	Connect SBE 33 to AC power source	1
80915	2-pin MS3106A-12S-3P to 2-pin RMG-2FS cable, 10 m (33 ft)	Connect <i>Sea Cable</i> on SBE 33 to Water Sampler or PDIM for testing	1
801367	4-pin MS3106A-14S-2P to 5-pin Switchcraft EN3C5F cable, 15 m (50 ft)	Connect <i>PAR Input</i> on SBE 33 to Biospherical Surface PAR sensor with Switchcraft connector	1

Appendix V: Manual Revision History

Manual Version	Date	Description
001	02/02	• Create separate manual for SBE 33 (had been combined with SBE 32 manual). SBE 33 manual provides detailed information on how to use SBE 33.SBE 32 manual now explains how to assemble and use Carousel, and provides brief description of each interface method.
002	05/02	• SBE 33 added to Seaterm's list of instruments; update Seaterm description.
003	11/02	• Correct power specification from 50/400 to 50/60 Hz.
		• Update use of NMEA simulation software to Windows version (NMEATest).
004	08/03	• Update to 9 pin computer connectors throughout.
		Update Surface PAR with new Biospherical product number
		Update Surface PAR wiring.
		• Add SBE 50 to use of 32 with AFM in general description of Carousel.
		• Add note that 2 nd RS-232 line required (Carousel data) to computer for Seasave to receive bottle
		fire confirmation from Carousel and create .ros file, even if not firing bottles through Seasave.
		Update .con file screen capture with new screen capture for current version of Seasave.
005	03/04	• Correct dip switch factory set in SBE 33 (CTD to carousel communications) to 4800 baud.
		Update for Seaterm changes
006	03/06	• NMEA firmware 2.3: allows selection of data bits and parity on PCB dip switch.
		Add detailed dimensional information and weight.
		• Add more information on accessing and setting dip switches.
		• Correct information about bottle confirm bit in modulo word – only true for 911plus, not for 33.
007	03/07	• Add information that can use 33 with SBE 55 ECO Water Sampler.
		• Add information that can use 49 with 32 (with serial interface) & 33 – no NMEA or Surface PAR.
		• Incorporate Seasave V7 – update all descriptions of how to set up & use Seasave, update 19plus
000	0.4/0.0	.con file screen capture to show 'scan time added' field
008	04/08	• Update SBE 55 schematic (frame change & ECM connectors at bottom).
		• Update for use with 19plus V2.
		• Update Seasave water sampler tab dialog box (remote firing now available); also mention ability
		to do mixed mode auto fire and to do auto fire on downcast.
		• Update .con dialog box for 19plus to show <i>NMEA depth data added</i> selection.
		• Update real-time data acquisition dialog box, showing selection for resetting to state 1 (echo only, no NMEA data) when cast complete.
009	02/09	 Update .con file screen capture for Seasave/Data Proc 7.18.
007	02/07	 Add note that NMEA can go directly to computer.
		 Add note to turn off CTD magnetic switch before stopping data acquisition, so putting deck unit
		back into state 1 is successful.
		 Delete references to SCPlusV2 terminal program, replaced with SeatermV2.
		 Add information about software compatibility with Vista.
		• Add information on 25 with 33 deck unit – if have NMEA + Surface PAR + > 4 voltages, deck
		unit cannot keep up. Set 25 to output real-time at 4 Hz or less (instead of 8 Hz maximum rate).
010	03/10	• Electronics redesign: 1 PCB, NMEA is standard. Dip switches are gone, replaced by commands.
		Serial Data and Carousel Data connectors now 9-pin; changed cables that ship with deck unit.
		Changes required for CE certification.
		• New photo and drawing of back panel.
		• Update software name.
		• Add information about .xmlcon file.
		• Seasave 7.19:
		- Allows acquisition of NMEA depth data for all profiling CTDs.
		- Allows acquisition of NMEA data for SBE 49.
		 Add information about unsupported modern message from Carousel. Add information that must be in Mode 1 (characters to/from CTD pass thru 33) if trying to send
		 Add information that must be in Mode 1 (characters to/from CTD pass thru 33) if trying to send command to CTD thru 33.
		 Update SBE address.
Continued	1	

Continued on next page

Manual revision 017

Continue	d from pre	evious page
011	03/12	Add information on use with SBE 25plus.
		• Add information about ordering cable, winch, and deck gear.
		Add more troubleshooting information.
		• Add information about software compatibility with Windows 7.
		• Add information about launching Seaterm from SeatermV2.
012	04/13	Add Declaration of Conformity.
		• Show Surface PAR as standard (was optional).
		Add cable and wiring diagrams.
		Update software compatibility information.
013	03/14	• Add information that Seasave 7.23.2 allows Surface PAR acquisition with SBE 49.
		• Add information on use of SBE 33 with PDIM in place of Water Sampler, when a Water Sampler
		is not available or needed.
		• Remove references to requiring Seasave version 7.19 or later (7.19 released > 4 years ago).
		Update Declaration of Conformity.
		Add caution on using spray can lubricants on MCBH connectors.
		• Remove <i>standard</i> and <i>optional</i> language for connectors.
		• Fix typos.
014	02/15	• Update photos and dimensions for new deck unit housing.
		• Update language on where to find updated software on website.
		• Update link to cable and winch supplier page on website.
		Switch to Sea-Bird Scientific cover.
015	05/16	• Add information that cannot close more than 24 bottles.
		• Correct weight.
		Add SeatermV2 main screen.
		Update Declaration of Conformity.
016	07/17	Add information on compatibility with Satlantic Surface PAR sensor.
		• Update information on configuration file that ships with instrument (.xmlcon file, not .con file).
		Switch to new Sea-Bird Scientific manual cover.
017	01/18	Included PDIM information from SBE 36 manual

.con file \cdot 28

.xmlcon file · 28

B

Back panel · 13 Baud rate · 17, 21, 32 Bottle firing \cdot 32, 36

С

Cables · 14, 29 CE certification · 3 Cleaning · 40 Communications · 17 Configuration file · 28 Connectors · 12, 40 CTD configuration file \cdot 28 setup \cdot 21, 24 upload · 38

D

Data bits · 17 Data processing \cdot 38 Data upload · 38 Deck gear · 29 Declaration of Conformity · 3 Description · 8 Dimensions · 11, 12

E

Editing data files · 39 Electrical symbols · 45 Electronics disassembly/reassembly · 50 End cap \cdot 40

F

Firing bottles · 32, 36 Front panel · 13

G

Glossary · 44

Ι

Installation · 29, 30

М

Maintenance · 40 Manual revision history · 52 Mounting · 29

N

NMEA · 18, 24, 31 data formats · 46 message formats \cdot 46 simulation program · 48 troubleshooting \cdot 43 NMEATest · 9, 20, 48

0

Operating modes · 18 Operating system · 32

Р

Parity · 17 Parts replacement · 51 PDIM · 8, 12, 17 connectors · 12 dimensions · 12 Processing data · 38

R

Real-time acquisition \cdot 32 Recovery · 37 Replacement parts · 51 Revision history · 52 Routine maintenance \cdot 40

S

Safety symbols · 45 **SBE 33** back panel · 13 front panel · 13 SBE Data Processing · 9, 20 Sea cable · 29 Seasave · 9, 20, 28, 32 Seasoft \cdot 9, 20 Seaterm · 9, 20, 21, 48 main screen \cdot 22 SeatermV2 · 9, 20 Setup · 24 Slip ring \cdot 29 Software · 9, 20 Specifications · 11 Surface PAR · 18, 31 System communications · 17 System description · 8 System operation \cdot 32 System wiring · 30

Т

Testing $\cdot 24$ Troubleshooting · 41 Manual revision 017

U

Unpacking SBE 33 · 7 Uploading data · 38

V

 $Versions\cdot\,52$

W

 $\begin{array}{l} Winch \cdot \ 29 \\ Wiring \cdot \ 14, \ 30 \end{array}$